









Power Consumption Running       3.5 W         Power Consumption Holding       2.5 W         Transformer Sizing       6 VA (class 2 power source)         Shaft Diameter $1/2$ " to 1.05" round, centers on $3/4$ " with insert, 1.05" without insert         Electrical Connection       3 ft [1 m], 18 GA appliance cable with $1/2$ " conduit connector         Overload Protection       electronic throughout 0° to 95° rotation         Electrical Protection       actuators are double insulated         Operating Range Y       2 to 10 VDC, 4 to 20 mA w/ ZG-R01 (500 G) $1/4$ W resistor)       100 k $\Omega$ for 2 to 10 VDC (0.1 mA), 500 $\Omega$ d/4 to 20 mA         Feedback Output U       2 to 10 VDC, 0.5 mA max         Angle of Rotation       95° (adjustable with mechanical end stop, 35° to 95°)         Torque       90 in-lbs [10 Nm] minimum	Technical Data	
$\begin{array}{c} \mbox{Power Consumption Holding} & 2.5 \ \mbox{W} \\ \mbox{Transformer Sizing} & 6 \ \mbox{VA (class 2 power source)} \\ \mbox{Shaft Diameter} & 1/2" \ \mbox{to } 1.05" \ \mbox{round, centers on } 3/4" \ \mbox{with insert, } 1.05" \ \mbox{without insert} \\ \mbox{Electrical Connection} & 3 \ \mbox{ft } [1 \ \mbox{m], } 18 \ \mbox{GA appliance cable with } 1/2" \ \mbox{conduit connector} \\ \mbox{Overload Protection} & electronic throughout 0° to 95° \ \mbox{rotation} \\ \mbox{Electrical Protection} & actuators are double insulated} \\ \mbox{Operating Range Y} & 2 \ \mbox{to } 10 \ \mbox{VDC, } 4 \ \mbox{to } 20 \ \mbox{mA} \ \mbox{W/ ZG-R01 (500 \ \mbox{GO)} 1/4 \ \mbox{W resistor)} \\ \mbox{Input Impedance} & 100 \ \mbox{k} \ \mbox{O} \ \mbox{for } 2 \ \mbox{to } 10 \ \mbox{VDC (0.1 mA), } 500 \ \mbox{O} \ \mbox{M} \\ \mbox{4 to } 20 \ \mbox{mA} \\ \mbox{Feedback Output U} & 2 \ \mbox{to } 10 \ \mbox{VDC, } 0.5 \ \mbox{mA} \ \mbox{max} \\ \mbox{Angle of Rotation} & 95° \ \mbox{(adjustable with mechanical end stop, } 35° \ \mbox{to } 95°) \\ \mbox{Torque} & 90 \ \mbox{in-lbs } [10 \ \mbox{Nm] minimum} \\   \mbox{minimum} \mbox{minimum} \\   \$	Power Supply	24 VAC±20%, 50/60Hz, 24 VDC+20%/-10%
$ \begin{array}{llllllllllllllllllllllllllllllllllll$	Power Consumption Running	3.5 W
$ \begin{array}{c} \text{Shaft Diameter} & 1/2\text{" to } 1.05\text{" round, centers on } 3/4\text{" with insert, } 1.05\text{" without insert} \\ \text{Electrical Connection} & 3 \text{ ft } [1 \text{ m}], 18 \text{ GA appliance cable with } 1/2\text{" conduit connector} \\ \text{Overload Protection} & \text{electronic throughout } 0^{\circ} \text{ to } 95^{\circ} \text{ rotation} \\ \text{Electrical Protection} & \text{actuators are double insulated} \\ \text{Operating Range Y} & 2 \text{ to } 10 \text{ VDC, } 4 \text{ to } 20 \text{ mA w/ ZG-R01 (500 \Omega)} \\ 1/4 \text{ W resistor)} \\ \text{Input Impedance} & 100 \text{ k} \Omega \text{ for } 2 \text{ to } 10 \text{ VDC (0.1 mA), } 500 \Omega \Omega$	Power Consumption Holding	2.5 W
$\begin{array}{c} \text{insert, 1.05" without insert} \\ \text{Electrical Connection} \\ \text{St [1 m], 18 GA appliance cable with 1/2"} \\ \text{conduit connector} \\ \text{Overload Protection} \\ \text{Electrical Protection} \\ \text{Electrical Protection} \\ \text{Operating Range Y} \\ \text{Input Impedance} \\ \text{Input Impedance} \\ \text{Input Impedance} \\ \text{Peedback Output U} \\ \text{Angle of Rotation} \\ \text{Angle of Rotation} \\ \text{Input Impedance} \\ Input Impedan$	Transformer Sizing	6 VA (class 2 power source)
$ \begin{array}{c} \text{Electrical Connection} & 3 \text{ ft } [1 \text{ m}], 18 \text{ GA appliance cable with } 1/2" \\ & \text{conduit connector} \\ \text{Overload Protection} & \text{electronic throughout 0° to } 95° \text{ rotation} \\ \text{Electrical Protection} & \text{actuators are double insulated} \\ \text{Operating Range Y} & 2 \text{ to } 10 \text{ VDC}, 4 \text{ to } 20 \text{ mA w/ ZG-R01 (500 Gold Molecular Solution)} \\ \text{Input Impedance} & 100 \text{ k} \Omega \text{ for } 2 \text{ to } 10 \text{ VDC (0.1 mA), } 500 \Omega \Omega$	Shaft Diameter	
$ \begin{array}{c} conduit\ connector \\ \hline Coverload\ Protection \\ \hline Electrical\ Protection \\ \hline Coverload\ Protection \\ \hline Electrical\ Protection \\ \hline Coverload\ $		
	Electrical Connection	
	Overdeed Ductostics	
$\begin{array}{c} \text{Operating Range Y} & 2 \text{ to 10 VDC, 4 to 20 mA w/ ZG-R01 (500 solid line)} \\ \text{Input Impedance} & 100 \text{ k } \Omega \text{ for 2 to 10 VDC (0.1 mA), 500 } \Omega \\ \text{4 to 20 mA} \\ \text{Feedback Output U} & 2 \text{ to 10 VDC, 0.5 mA max} \\ \text{Angle of Rotation} & 95^{\circ} \text{ (adjustable with mechanical end stop, 35}^{\circ} \text{ to 95}^{\circ}) \\ \text{Torque} & 90 \text{ in-lbs [10 Nm] minimum} \\ \end{array}$		
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Operating Range Y	
Feedback Output U 2 to 10 VDC, 0.5 mA max  Angle of Rotation 95° (adjustable with mechanical end stop, 35° to 95°)  Torque 90 in-lbs [10 Nm] minimum	Input Impadance	
Feedback Output U 2 to 10 VDC, 0.5 mA max  Angle of Rotation 95° (adjustable with mechanical end stop, 35° to 95°)  Torque 90 in-lbs [10 Nm] minimum	iliput illipedalice	
Angle of Rotation 95° (adjustable with mechanical end stop, 35° to 95°)  Torque 90 in-lbs [10 Nm] minimum	Feedback Output II	
35° to 95°) Torque 90 in-lbs [10 Nm] minimum	·	
Torque 90 in-lbs [10 Nm] minimum	7 mgro or riotation	
	Torque	
	Direction of Rotation (Motor)	
Direction of Rotation (Fail-Safe) reversible with CW/CCW mounting	Direction of Rotation (Fail-Safe)	reversible with CW/CCW mounting
Position Indication dial	Position Indication	dial
Manual Override 5 mm hex crank (3/16" Allen), supplied	Manual Override	5 mm hex crank (3/16" Allen), supplied
Running Time (Motor) 95 sec	Running Time (Motor)	95 sec
	Running Time (Fail-Safe)	<20 sec @ -4°F to 122°F [-20°C to 50°C], <
60 sec @ -22°F [-30°C]		L 1
Humidity 100% condensing	•	
Ambient Temperature Range -22°F to +122°F [-30°C to +50°C]		
Storage Temperature Range -40°F to +176°F [-40°C to +80°C]		
Housing NEMA 4, IP66, UL enclosure type 4	Housing	NEMA 4, IP66, UL enclosure type 4
Housing Material polycarbonate	Housing Material	polycarbonate
Agency Listings† cULus acc. to UL60730-1A/-2-14, CAN/CS E60730-1:02, CE acc. to 2004/108/EC	Agency Listings†	cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2004/108/EC
Noise Level (Motor) ≤40 dB (A)	Noise Level (Motor)	
Noise Level (Fail-Safe) <62 dB (A)	Noise Level (Fail-Safe)	<62 dB (A)
Servicing maintenance free	Servicing	maintenance free
Quality Standard ISO 9001	Quality Standard	ISO 9001

†Rated Impulse Voltage 800V, Type of action 1.AA, Control Pollution Degree 4.

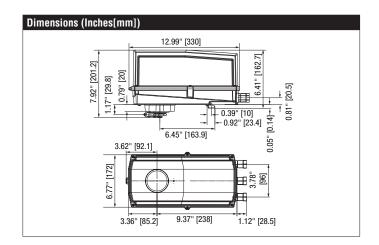
Torque min. 90 in-lb, for control of air dampers.

#### **Application**

For modulation of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. The actuator is mounted directly to a damper shaft up to 1.05" in diameter by means of its universal clamp. The actuator operates in response to a 2 to 10 VDC, with the addition of a  $500\Omega$  resistor, a 4 to 20 mA control input from an electronic controller or positioner. A 2 to 10 VDC feedback signal is provided for position indication. Not to be used for a master-slave application.

## Operation

The NF..24-SR N4 series actuators provide true spring return operation for reliable fail-safe application and positive close off on air tight dampers. The spring return system provides constant torque to the damper with, and without, power applied to the actuator. The NF.24-SR N4 series provides 95° of rotation and is provided with a graduated position indicator showing 0° to 95°. The NF. 24-SR N4 uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuator's exact fail-safe position. The ASIC monitors and controls the brushless DC motor's rotation and provides a digital rotation sensing function to prevent damage to the actuator in a stall condition. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. The NF..24-SR N4 actuator is shipped at +5° (5° from full fail-safe) to provide automatic compression against damper gaskets for tight shut-off.



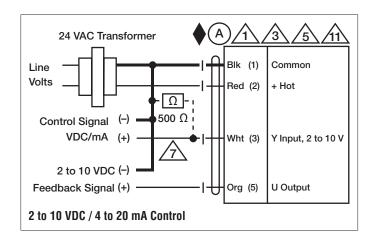
## NFB24-SR N4 - Damper Actuator

NEMA 4, Modulating, Spring Return, 24 V, for 2 or 10 VDC or 4 to 20 mA Control Signal

Accessories	
AF-P	Anti-rotation bracket AF/NF.
KG10A	Ball joint for 3/8" diameter rod, zinc plated.
KH10	Univ. crankarm, slot 21/64" w, for 9/16" to 1" dia. shafts.
SH10	Push rod for KG10A ball joint (36" L, 3/8" diameter).
T00L-06	8 mm and 10 mm wrench.
T00L-07	13 mm wrench.
ZG-DC1	Damper clip for damper blade, 3.5" width.
ZG-DC2	Damper clip for damper blade, 6" width.
ZG-JSA-1	1" diameter jackshaft adaptor (11" L).
ZG-JSA-2	1-5/16" diameter jackshaft adaptor (12" L).
ZG-JSA-3	1.05" diameter jackshaft adaptor (12" L).
11097-00001	Gasket for cable gland (for NEMA 4 models).
43442-00001	Cable gland (for NEMA 4 models).
ADS-100	Analog to digital switch for modulating actuators.
IRM-100	Input rescaling module for modulating actuators.
PS-100	Actuator power supply and control simulator.
PTA-250	Pulse width modulation interface for modulating actuators.
SGA24	Positioner control for modualting actuators (surface mount).
SGF24	Positioner control for modulating actuators (flush mount).
ZG-R01	4 to 20 mA adaptor, 500Ω, 1/4 W resistor w 6" pigtail wires.
ZG-R02	50% voltage divider kit (resistors with wires).
ZG-SGF	Mounting plate for SGF.
ZG-X40	120 to 24 VAC, 40 VA transformer.

#### Typical Specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a 1.05" diameter. The actuator must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a  $500\Omega$  resistor, a 4 to 20 mA control input from an electronic controller or positioner. The actuators must be designed so that they may be used for either clockwise or counter clockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback. Actuators with auxiliary switches must be constructed to meet the requirements for Double Insulation so an electrical ground is not required to meet agency listings. Actuators shall be cULus listed and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.



# NFB24-SR N4 - Damper Actuator



NEMA 4, Modulating, Spring Return, 24 V, for 2 or 10 VDC or 4 to 20 mA Control Signal

## Wiring Diagrams



## WARNING! LIVE ELECTRICAL COMPONENTS!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.



Meets cULus requirements without the need of an electrical ground connection.



Actuators with appliance cables are numbered.



Provide overload protection and disconnect as required.



Actuators may also be powered by 24 VDC.



Only connect common to negative (-) leg of control circuits.



A 500  $\Omega$  resistor (ZG-R01) converts the 4 to 20 mA control signal to 2



Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.