Modulating, Spring Return, 24 V, 0 to 135  $\Omega$ 













Techn	ical	data
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Input

Electrical data	Nominal voltage	AC/DC 24 V	
	Nominal voltage frequency	50/60 Hz	
	Power consumption in operation	7.5 W	
	Power consumption in rest position	3 W	
	Power consumption for wire sizing	10 VA	
	Transformer sizing	10 VA (class 2 power source)	
	Electrical Connection	18 GA plenum cable, 3 ft [1 m], with 1/2"	
		conduit connector	
	Overload Protection	electronic throughout 095° rotation	
	Electrical Protection	actuators are double insulated	
Functional data	Torque motor	180 in-lb [20 Nm]	
	Operating range Y	0135 Ω	
	Operating range Y note	Honeywell Electronic Series 90, input 0135 $\Omega$	
	Position feedback U	210 V	
	Position feedback U note	Max. 0.5 mA	
	Position feedback U variable	VDC variable	
	Direction of motion motor	selectable with switch 0/1	
	Direction of motion fail-safe	reversible with cw/ccw mounting	
	Manual override	5 mm hex crank (3/16" Allen), supplied	
	Angle of rotation	95°	
	Angle of rotation note	adjustable with mechanical end stop, 3595°	
	Running Time (Motor)	150 s / 90°	
	Running time motor variable	70220 s	
	Running time fail-safe	<20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]	
	Angle of rotation adaptation	off (default)	
	Override control	MIN (minimum position) = 0% MID (intermediate position) = 50%	
	Notes Issuel and an	MAX (maximum position) = 100%	
	Noise level, motor	40 dB(A)	
	Noise level, fail-safe	62 dB(A)	
	Shaft Diameter	1/21.05" round, centers on 1/2" and 3/4" with insert, 1.05" without insert	
	Position indication	Mechanical	
Safety data	Degree of protection IEC/EN	IP54	
	Degree of protection NEMA/UL	NEMA 2	
	Fnclosure	UL Enclosure Type 2	



	Technical data sheet	AFB24-MFT95
Safety data	Agency Listing	cULus listed to UL60730-1A:02; UL 60730-2-14:02 and CAN/CSA-E60730-1:02; Listed to UL 2043 - suitable for use in air plenums per Section 300.22(c) of the NEC and Section 602.2 of the IMC
	Quality Standard	ISO 9001
	Ambient temperature	-22122°F [-3050°C]
	Storage temperature	-40176°F [-4080°C]
	Ambient humidity	Max. 95% RH, non-condensing
	Servicing	maintenance-free
Weight	Weight	4.1 lb [1.9 kg]

Materials

**Footnotes** 

\*Variable when configured with MFT options.

Housing material

†Rated Impulse Voltage 800V, Type of action 1.AA, Control Pollution Degree 3

# **Product features**

# **Default/Configuration**

Default parameters for 0 to  $135\Omega$  input applications of the AF..-MFT95 actuator are assigned during manufacturing. If required, custom versions of the actuator can be ordered, however the control input cannot be modified via MFT PC tool software. The other parameters are variable and can be changed by three means: Factory pre-set or custom configuration, set by the customer using PC-Tool software or the handheld ZTH US.

Galvanized steel and plastic housing

# **Application**

For fail-safe, modulating control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. A feedback signal is provided for position indication for master-slave applications. Two AF's can be piggybacked for torque loads of up to 360 in-lbs. Minimum 3/4" diameter shaft. OR Maximum of three AF's can be piggybacked for torque loads of up to 432 in-lbs. Minimum 3/4" diameter shaft. Master-Slave wiring for either configuration.

# Operation

The AF..24-MFT95 actuator provides 95° of rotation and is provided with a graduated position indicator showing 0° to 95°. The actuator will synchronize the 0° mechanical stop or the physical damper or valve mechanical stop and use this point for its zero position during normal control operations. A unique manual override allows the setting of any actuator position within its 95° of rotation with no power applied. This mechanism can be released physically by the use of a crank supplied with the actuator. When power is applied the manual override is released and the actuator drives toward the fail-safe position. The actuator uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuator's exact position. The ASIC monitors and controls the brushless DC motor's rotation and provides a Digital Rotation Sensing (DRS) function to prevent damage to the actuator in a stall condition. The position feedback signal is generated without the need for mechanical feedback potentiometers using DRS. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. The AF..24-MFT95 is mounted directly to control shafts up to 1.05" diameter by means of its universal clamp and anti-rotation bracket. A crank arm and several mounting brackets are available for damper applications where the actuator cannot be direct coupled to the damper shaft. The spring return system provides minimum specified torque to the application during a power interruption. The AF..24-MFT95 actuator is shipped at 5° (5° from full fail-safe) to provide automatic compression against damper gaskets for tight shut-off.







### Typical specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a 1.05" diameter. The actuator must provide modulating damper control in response to a 0 to 135 ohm control input from a Honeywell Series 90 controller or equivalent. The actuators must be designed so that they may be used for either clockwise or counter clockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback or master slave applications. Actuators shall be cULus listed and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

# **Factory settings**

Default parameters for 0 to  $135\Omega$  input applications of the AF..-MFT95 actuator are assigned during manufacturing. If required, custom versions of the actuator can be ordered, however the control input cannot be modified via MFT PC tool software. The other parameters are variable and can be changed by three means: Factory pre-set or custom configuration, set by the customer using PC-Tool software or the handheld ZTH US.

# Accessories

Electrical accessories	Description	Туре
	Auxiliary switch, mercury-free	P475
	Auxiliary switch, mercury-free	P475-1
	Cable conduit connector 1/2"	TF-CC US
	Resistor kit, for -MFT95 actuator in 0135 $\Omega$ control application	ZG-R03
	Transformer, AC 120 V to AC 24 V, 40 VA	ZG-X40



#### **Technical data sheet** AFB24-MFT95

# Mechanical accessories

Description	Туре
Anti-rotation bracket, for AF / NF	AF-P
Shaft extension 240 mm Ø20 mm for damper shaft Ø 822.7 mm	AV8-25
End stop indicator	IND-AFB
Shaft clamp reversible, for central mounting, for damper shafts Ø12.7 /	K7-2
19.0 / 25.4 mm	
Ball joint suitable for damper crank arm KH8 / KH10, Multipack 10 pcs.	KG10A
Ball joint suitable for damper crank arm KH8, Multipack 10 pcs.	KG8
Damper crank arm Slot width 8.2 mm, clamping range Ø1425 mm	KH10
Damper crank arm Slot width 8.2 mm, for Ø1.05"	KH12
Damper crank arm Slot width 8.2 mm, clamping range Ø1018 mm	KH8
Actuator arm, for 3/4" shafts, clamping range Ø1022 mm, Slot width 8.2	KH-AFB
mm	
Push rod for KG10A ball joint 36" L, 3/8" diameter	SH10
Push rod for KG6 & KG8 ball joints (36" L, 5/16" diameter).	SH8
Wrench 0.32 in and 0.39 in [8 mm and 10 mm]	TOOL-06
Retrofit clip	Z-AF
17" Mounting Bracket for AF,NF,GM,AM,SM	ZG-100
Mounting Bracket: AF,NF,LF,GM,AM,NM,SM	ZG-101
Dual actuator mounting bracket.	ZG-102
Mounting Bracket: ZS-260 Right Angle	ZG-109
Linkage kit	ZG-110
Mounting bracket	ZG-118
for AF / NF	
ackshaft mounting bracket.	ZG-120
Mounting kit for linkage operation for flat and side installation	ZG-AFB
Mounting kit for foot mount installation	ZG-AFB118
Damper clip for damper blade, 3.5" width.	ZG-DC1
Damper clip for damper blade, 6" width.	ZG-DC2
1" diameter jackshaft adaptor (11" L).	ZG-JSA-1
1-5/16" diameter jackshaft adaptor (12" L).	ZG-JSA-2
1.05" diameter jackshaft adaptor (12" L).	ZG-JSA-3
Weather shield 330x203x152 mm [13x8x6"] (LxBxH)	ZS-100
Base plate, for ZS-100	ZS-101
Weather shield 406x213x102 mm [16x8-3/8x4"] (LxWxH)	ZS-150
Explosion proof housing 406x254x164 mm [16x10x6.435"] (LxBxH), UL	ZS-260
and CSA, Class I, Zone 1&2, Groups B, C, D, (NEMA 7), Class III, Hazardous	
(classified) Locations	75.000
Weather shield 438x222x140 mm [17-1/4x8-3/4x5-1/2"] (LxBxH), NEMA	ZS-300
4X, with mounting brackets	75 200 5
Weather shield 438x222x140 mm [17-1/4x8-3/4x5-1/2"] (LxBxH), NEMA	ZS-300-5
4X, with mounting brackets	75 200 54
Shaft extension 1/2"	ZS-300-C1
Shaft extension 3/4"	ZS-300-C2
Shaft extension 1"	ZS-300-C3
Base plate extension	Z-SF
	ZG-JSL
Description	Туре
Belimo PC-Tool, Software for adjustments and diagnostics	MFT-P
Signal simulator, Power supply AC 120 V	PS-100
Connection cable 16 ft [5 m], A: RJ11 6/4 ZTH EU, B: free wire end for	ZK2-GEN
connection to MP/PP terminal	
Service Tool, with ZIP-USB function, for programmable and	ZTH US
communicative Belimo actuators, VAV controller and HVAC performance	
devices	

# **Electrical installation**



Service tools

# Marning! Live electrical components!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks.



Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.

Meets cULus requirements without the need of an electrical ground connection.

A Provide overload protection and disconnect as required.

Actuators may also be powered by DC 24 V.

 $\sqrt{22}$  Actuators and controller must have separate transformers.

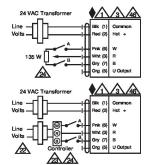
Consult controller instruction data for more detailed information.

A Resistor value depends on the type of controller and the number of actuators. No resist

Resistor value depends on the type of controller and the number of actuators. No resistor is used for one actuator. Honeywell® resistor kits may also be used.

 $\frac{1}{25}$  To reverse control rotation, use the reversing switch.

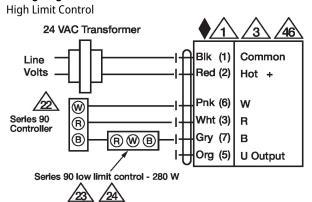
Actuators may be controlled in parallel. Current draw and input impedance must be observed.

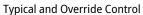


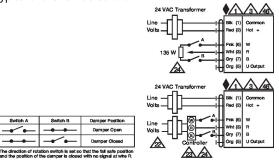
Damper Open
Demper Closed
The direction of rotation switch is set so that the fall sets position and the position of the damper is closed with no signal at wives R.

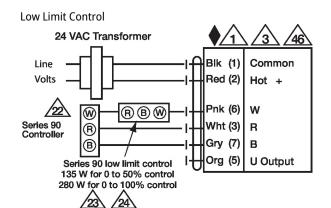
Typical and Override Control

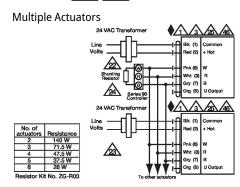
# Wiring diagrams





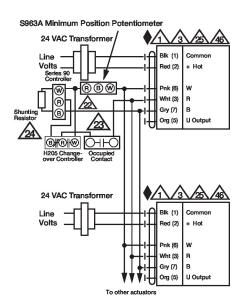


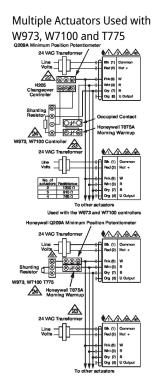






Multiple Actuators with Minimum Position Potentiometer





# **Dimensions**

