



5-year warranty



Technical data

Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Power consumption in operation	2.5 W
	Power consumption in rest position	0.5 W
	Power consumption for wire sizing	4.5 VA
	Transformer sizing	4.5 VA (class 2 power source)
	Electrical Connection	18 GA plenum cable, 3 ft [1 m], with 1/2" conduit connector
	Overload Protection	electronic throughout full stroke
Functional data	Actuating force motor	450 N [100 lbf]
	Operating range Y	2...10 V
	Operating range Y note	4...20 mA w/ ZG-R01 (500 Ω, 1/4 W resistor)
	Input Impedance	100 kΩ for 2...10 V (0.1 mA), 500 Ω for 4...20 mA
	Position feedback U	2...10 V
	Position feedback U note	Max. 0.5 mA
	Direction of motion motor	reversible with switch
	Manual override	external push button
	Stroke	4" [100 mm]
	Running Time (Motor)	150 s / 100 mm
	Noise level, motor	35 dB(A)
Safety data	Degree of protection IEC/EN	IP54
	Degree of protection NEMA/UL	NEMA 2
	Enclosure	UL Enclosure Type 2
	Agency Listing	cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2014/30/EU and 2014/35/EU; Listed to UL 2043 - suitable for use in air plenums per Section 300.22(c) of the NEC and Section 602.2 of the IMC
	Quality Standard	ISO 9001
	Ambient temperature	-22...122°F [-30...50°C]
	Storage temperature	-40...176°F [-40...80°C]
	Ambient humidity	Max. 95% RH, non-condensing
	Servicing	maintenance-free
Materials	Housing material	UL94-5VA

Footnotes †Rated Impulse Voltage 800V, Type of Action 1, Control Pollution Degree 2.






Product features

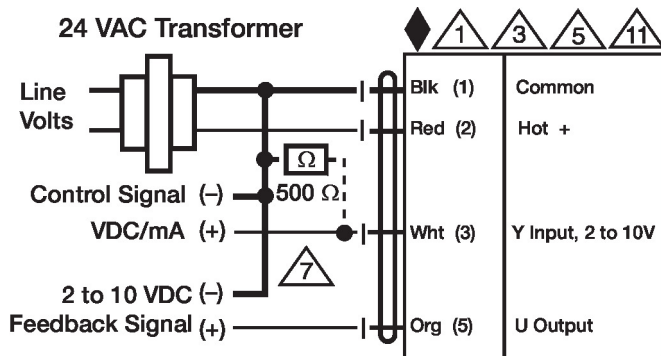
Application	<p>For proportional modulation of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. The actuator operates in response to a 2...10 V, or with the addition of a 500 Ω resistor, a 4...20 mA control input from an electronic controller or positioner.</p> <p>A 2...10 V feedback signal is provided for position indication or master-slave applications.</p>
Operation	<p>The actuator is not provided with and does not require any limit switches, but is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement. The actuator provides 4" [100 mm] of linear stroke. The stroke of the gear rack can be adjusted on both sides in increments of 0.8 in [20 mm] by means of the mechanical end stops. When reaching the damper or actuator end position, the actuator automatically stops. The gears can be manually disengaged with a button on the actuator cover. The actuators use a sensorless brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in holding mode.</p>
Typical specification	<p>Proportional control damper actuators shall be electronic direct-coupled type, which require no crank arm and linkage and be capable of direct mounting to a shaft up to 3/4" diameter. Actuators must provide proportional damper control in response to a 2 to 10 VDC or, with the addition of a 500 Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. Actuators shall have brushless DC motor technology and be protected from overload at all angles of rotation. Actuators shall have reversing switch and manual override on the cover. If required, actuator will be provided with screw terminal strip for electrical connections (AMX24-SR-T and NMX24-SR-T). Run time shall be constant and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position indication. Actuators shall be cULus listed, have a 5-year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.</p>

Accessories

Electrical accessories	Description	Type
	<p>DC Voltage Input Rescaling Module</p>	IRM-100
	Signal simulator, Power supply AC 120 V	PS-100
	<p>Convert Pulse Width Modulated Signal to a 2...10 V Signal for Belimo Proportional Actuators</p>	PTA-250
	Positioner for wall mounting	SGA24
	Positioner for front-panel mounting	SGF24
	Cable conduit connector 1/2"	TF-CC US
	Resistor, 500 Ω , 1/4" wire resistor with 6" pigtail wires	ZG-R01
	Resistor kit, 50% voltage divider	ZG-R02
	Transformer, AC 120 V to AC 24 V, 40 VA	ZG-X40
	Battery backup system, for non-spring return models	NSV24 US
	Battery, 12 V, 1.2 Ah (two required)	NSV-BAT
Mechanical accessories	Description	Type
	Ball joint suitable for damper crank arm KH8 / KH10, Multipack 10 pcs.	KG10A
	Ball joint suitable for damper crank arm KH8, Multipack 10 pcs.	KG6
	Ball joint suitable for damper crank arm KH8, Multipack 10 pcs.	KG8
	Push rod for KG6 & KG8 ball joints (36" L, 5/16" diameter).	SH8
	Rotary support, for linear actuator, for compensation of transverse forces	Z-DS1
	3/8"-16 shaft clevis for AHK/AH.	Z-KSC
	Bracket for AHK/AH/LH linear actuators.	ZG-119

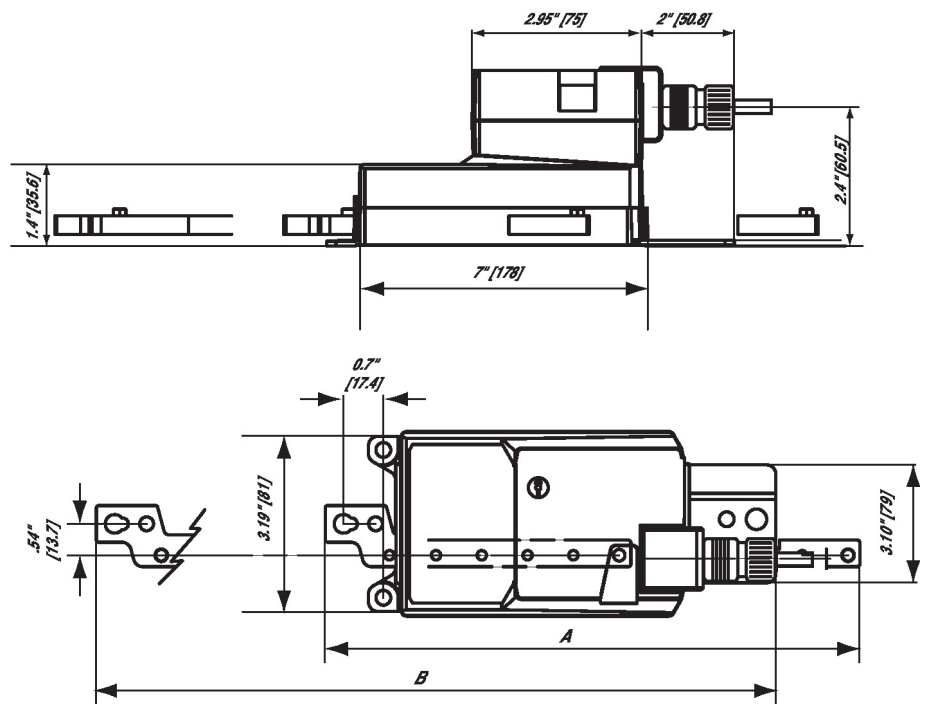
Electrical installation

-  Provide overload protection and disconnect as required.
-  Actuators may also be powered by DC 24 V.
-  Only connect common to negative (-) leg of control circuits.
-  A 500 Ω resistor (ZG-R01) converts the 4...20 mA control signal to 2...10 V.
-  Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.



2...10 V / 4...20 mA Control

Dimensions



<i>Stroke</i>	<i>A</i>	<i>B</i>
4" [100]	9.2" [233.5]	8" [294.7]
8" [200]	13.1" [333.5]	12" [394.7]
12" [300]	17.1" [433.5]	16" [494.7]