

# Chrome Plated Brass Ball and Nickel Plated Brass Stem





Type overview	
Туре	DN
B320L	20

### **Technical data**

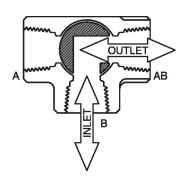
Functional data	Valve size [mm]	0.75" [20]
	Fluid	chilled or hot water, up to 60% glycol
	Fluid Temp Range (water)	0250°F [-18120°C]
	Body Pressure Rating	600 psi
	Close-off pressure Δps	200 psi
	Flow characteristic	modified linear
	Servicing	maintenance-free
	Flow Pattern	3-way Diverting
	Leakage rate	0%
	Controllable flow range	75°
	Cv	12.8
Materials	Valve body	Nickel-plated brass body
	Spindle	nickel-plated brass
	Seat	PTFE
	Pipe connection	NPT female ends
	Ball	chrome plated brass
Suitable actuators	Non-Spring	LRB(X)
	Spring	LF

## **Product features**

**Application** 

This valve is typically used in air handling units on heating or cooling coils, and fan coil unit heating or cooling coils. Some other common applications include Unit Ventilators, VAV box reheat coils and bypass loops. This valve is suitable for use as diverting or change over valve.

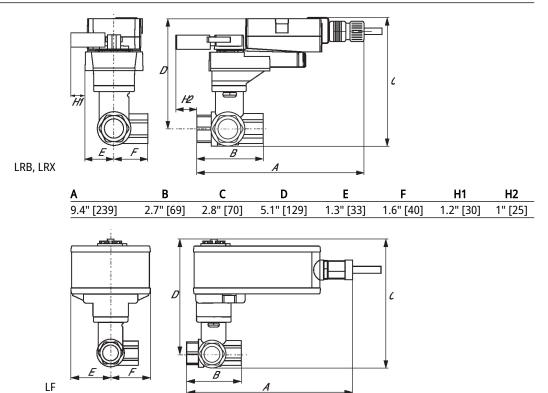
## Flow/Mounting details





# **Dimensions**

Туре	DN
B320L	20



C

6.3" [159]

В

2.7" [69]

<u>A</u> 8.6" [218] D

5.6" [142]

Ε

1.8" [46]

1.9" [48]



Modulating, Spring Return, 24 V, Multi-Function Technology®

Proportional, Spring Return, Multi-Function Technology®, Torque min. 35 in-lb, Control 2 to 10 VDC (DEFAULT), Feedback 2 to 10 VDC (DEFAULT)

# **Technical data sheet**







5-year warranty





Tach	nical	data
ICUI	ıııcaı	uata

Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Power consumption in operation	2.5 W
	Power consumption in rest position	1 W
	Transformer sizing	5 VA (class 2 power source)
	Electrical Connection	18 GA appliance cable, 3 ft [1 m], with 1/2" conduit connector
	Overload Protection	electronic throughout 095° rotation
	Electrical Protection	actuators are double insulated
Functional data	Torque motor	35 in-lb [4 Nm]
	Operating range Y	210 V
	Operating range Y note	420 mA w/ ZG-R01 (500 Ω, 1/4 W resistor)
	Input Impedance	100 k $\Omega$ for 210 V (0.1 mA), 500 $\Omega$ for 420 mA, 1500 $\Omega$ for PWM, On/Off and Floating point
	Operating range Y variable	Start point 0.530 V End point 2.532 V
	Options positioning signal	variable (VDC, PWM, on/off, floating point)
	Position feedback U	210 V
	Position feedback U note	Max. 0.5 mA
	Position feedback U variable	VDC variable
	Direction of motion motor	selectable with switch 0/1
	Direction of motion fail-safe	reversible with cw/ccw mounting
	Angle of rotation	 Max. 95°
	Angle of rotation note	adjustable with mechanical stop
	Running Time (Motor)	150 s / 90°
	Running time motor variable	75300 s
	Running time fail-safe	<25 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]
	Angle of rotation adaptation	off (default)
	Override control	MIN (minimum position) = 0% MID (intermediate position) = 50% MAX (maximum position) = 100%
	Noise level, motor	30 dB(A)
	Noise level, fiail-safe	62 dB(A)
	Shaft Diameter	3/81/2" round, centers on 1/2"
	Position indication	Mechanical
Safety data	Degree of protection IEC/EN	IP54
	Degree of protection NEMA/UL	NEMA 2
	Enclosure	UL Enclosure Type 2



	Technical data sheet		LF24-MFT US
cULus acc. To UL 873 and CAN/CSA C24-93; Listed to UL 2043 - suitable for plenums per Section 300.22(c) of the Section 602.2 of the IMC		sted to UL 2043 - suitable for use in air per Section 300.22(c) of the NEC and	
	Quality Standard	ISO 9001	
	Ambient temperature	-22122	°F [-3050°C]
	Storage temperature	-40176	°F [-4080°C]
	Ambient humidity	Max. 95%	6 RH, non-condensing
	Servicing	maintena	ance-free

Materials

**Footnotes** 

Housing material

Sa

\*Variable when configured with MFT options.

†Rated Impulse Voltage 800V, Type of action 1.AA, Control Pollution Degree 3

### **Product features**

### Default/Configuration

Default parameters for 2 to 10 VDC applications of the LF..-MFT actuator are assigned during manufacturing. If required, custom versions of the actuator can be ordered. The parameters are variable and can be changed by three means: Factory pre-set or custom configuration, set by the customer using PC-Tool software or the handheld ZTH US.

galvanized steel

#### **Application**

For fail-safe, modulating control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. A feedback signal is provided for position indication.

#### Operation

The LF24-MFT US actuator provides 95° of rotation and is provided with a graduated position indicator showing 0° to 95°. The actuator will synchronize the 0° mechanical stop or the damper or valves mechanical stop and use this point for its zero position during normal control operations. The actuator uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuator's exact position. The ASIC monitors and controls the brushless DC motor's rotation and provides a Digital Rotation Sensing (DRS) function to prevent damage to the actuator in a stall condition. The position feedback signal is generated without the need for mechanical feedback potentiometers using DRS. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. The LF24-MFT US is mounted directly to control shafts up to 3/4" diameter (K6-1 clamp) and anti-rotation bracket. A crank arm and several mounting brackets are available for damper applications where the actuator cannot be direct coupled to the damper shaft. The spring return system provides minimum specified torque to the application during a power interruption. The LF24-MFT US actuator is shipped in the zero position, compression against seats or gaskets for tight shut-off is accomplished manually.

### Typical specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a shaft up to a 3/4" diameter and center on a 1/2" shaft (default). Actuator shall deliver a minimum output torque of 35 in-lbs. The actuator must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a  $500\Omega$  resistor, a 4 to 20 mA control input from an electronic controller or positioner. The actuators must be designed so that they may be used for either clockwise or counter clockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback. Actuators with auxiliary switches must be constructed to meet the requirements for Double Insulation so an electrical ground is not required to meet agency listings. Actuators shall be cULus listed and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

### **Factory settings**

Default parameters for 2 to 10 VDC applications of the LF..-MFT actuator are assigned during manufacturing. If required, custom versions of the actuator can be ordered. The parameters are variable and can be changed by three means: Factory pre-set or custom configuration, set by the customer using PC-Tool software or the handheld ZTH US.



# Accessories

Gateways	Description	Туре
	Gateway MP to BACnet MS/TP	UK24BAC
	Gateway MP to Modbus RTU	UK24MOD
	Gateway MP to LonWorks	UK24LON
Electrical accessories	Description	Туре
	Coping States of the states	IRM-100
	Auxiliary switch, mercury-free	P475
	Auxiliary switch, mercury-free	P475-1
	Convert Pulse Width Modulated Signal to a 210 V Signal for Belimo	PTA-250
	Proportional Actuators	
	Positioner for wall mounting	SGA24
	Positioner for front-panel mounting	SGF24
	Gateway MP to BACnet MS/TP	UK24BAC
	Gateway MP to LonWorks	UK24LON
	Gateway MP to Modbus RTU	UK24MOD
	Resistor, 500 Ω, 1/4" wire resistor with 6" pigtail wires	ZG-R01
	Resistor kit, 50% voltage divider	ZG-R02
	Transformer, AC 120 V to AC 24 V, 40 VA	ZG-X40



#### **Technical data sheet** LF24-MFT US

#### Mechanical accessories

Description	Туре
Shaft extension 170 mm Ø10 mm for damper shaft Ø 616 mm	AV6-20
End stop indicator	IND-LF
Shaft clamp	K6 US
for LF	
Shaft clamp reversible, clamping range Ø1620 mm	K6-1
Ball joint suitable for damper crank arm KH8 / KH10, Multipack 10 pcs.	KG10A
Ball joint suitable for damper crank arm KH8, Multipack 10 pcs.	KG6
Ball joint suitable for damper crank arm KH8, Multipack 10 pcs.	KG8
Damper crank arm Slot width 8.2 mm, for Ø1.05"	KH12
Damper crank arm Slot width 6.2 mm, clamping range Ø1018 mm	KH6
Damper crank arm Slot width 8.2 mm, clamping range Ø1018 mm	KH8
Actuator arm, clamping range Ø816 mm, Slot width 8.2 mm	KH-LF
V-bolt Kit for KH-LF.	KH-LFV
Anti-rotation bracket LF.	LF-P
Push rod for KG10A ball joint 36" L, 3/8" diameter	SH10
Push rod for KG6 & KG8 ball joints (36" L, 5/16" diameter).	SH8
Wrench 0.32 in and 0.39 in [8 mm and 10 mm]	TOOL-06
Angle of rotation limiter, with end stop	ZDB-LF
Form fit adapter 8x8 mm	ZF8-LF
Mounting Bracket: ZS-260 Right Angle	ZG-109
Linkage kit	ZG-110
Mounting bracket	ZG-112
for LF	
Damper clip for damper blade, 3.5" width.	ZG-DC1
Damper clip for damper blade, 6" width.	ZG-DC2
LF crankarm adaptor kit (includes ZG-112).	ZG-LF112
LF crankarm adaptor kit (T bracket included).	ZG-LF2
Shaft extension for 3/8" diameter shafts (4" L).	ZG-LMSA-1
Shaft extension for 1/2" diameter shafts (5" L).	ZG-LMSA-1/2-5
Weather shield 330x203x152 mm [13x8x6"] (LxBxH)	ZS-100
Base plate, for ZS-100	ZS-101
Weather shield 406x213x102 mm [16x8-3/8x4"] (LxWxH)	ZS-150
Explosion proof housing 406x254x164 mm [16x10x6.435"] (LxBxH), UL	ZS-260
and CSA, Class I, Zone 1&2, Groups B, C, D, (NEMA 7), Class III, Hazardous	
(classified) Locations	
Weather shield 438x222x140 mm [17-1/4x8-3/4x5-1/2"] (LxBxH), NEMA	ZS-300
4X, with mounting brackets	75 200 5
Weather shield 438x222x140 mm [17-1/4x8-3/4x5-1/2"] (LxBxH), NEMA	ZS-300-5
4X, with mounting brackets	75 200 54
Shaft extension 1/2"	ZS-300-C1
Shaft extension 3/4"	ZS-300-C2
Shaft extension 1"	ZS-300-C3
Description	Туре
Connection cable 16 ft [5 m], A: RJ11 6/4 ZTH EU, B: free wire end for	ZK2-GEN
connection to MP/PP terminal	
Connection cable 10 ft [3 m], A: RJ11 6/4 ZTH EU, B: 3-pin Weidmüller and	ZK4-GEN
supply connection	
Service Tool, with ZIP-USB function, for programmable and	ZTH US
communicative Belimo actuators, VAV controller and HVAC performance	
devices	
Belimo PC-Tool, Software for adjustments and diagnostics	MFT-P
Signal simulator, Power supply AC 120 V	PS-100

# **Electrical installation**



Service tools

# Marning! Live electrical components!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.



**♦** V

Meets cULus requirements without the need of an electrical ground connection.

(A) Actuators with appliance cables are numbered.

Provide overload protection and disconnect as required.

🐧 Actuators may also be powered by DC 24 V.

6 Only connect common to negative (-) leg of control circuits.

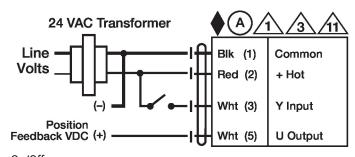
 $\Lambda$  A 500  $\Omega$  resistor (ZG-R01) converts the 4...20 mA control signal to 2...10 V.

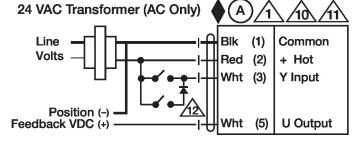
Control signal may be pulsed from either the Hot (Source) or Common (Sink) 24 V line.

For triac sink the Common connection from the actuator must be connected to the Hot connection of the controller. Position feedback cannot be used with a triac sink controller; the actuator internal common reference is not compatible.

Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.

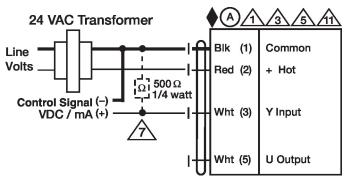
🛕 IN4004 or IN4007 diode. (IN4007 supplied, Belimo part number 40155).



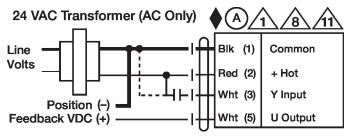


Floating Point

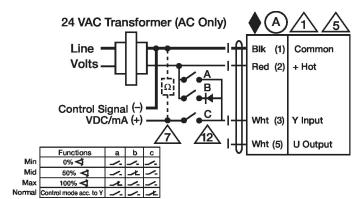
On/Off



VDC/mA Control



**PWM Control** 



Override Control



# **Dimensions**

