

On/Off, Floating Point, Non-Spring Return, 24 v







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Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Power consumption in operation	1.5 W
	Power consumption in rest position	0.2 W
	Transformer sizing	2.5 VA (class 2 power source)
	Electrical Connection	18 GA plenum cable with 1/2" conduit connector, degree of protection NEMA 2 / IP54, 3 ft [1 m] 10 ft [3 m] and 16ft [5 m]
	Overload Protection	electronic throughout 095° rotation
Functional data	Torque motor	45 in-lb [5 Nm]
	Direction of motion motor	selectable with switch 0/1
	Manual override	external push button
	Angle of rotation	Max. 95°
	Angle of rotation note	adjustable with mechanical stop
	Running Time (Motor)	95 s / 90°
	Running time motor note	constant, independent of load
	Running time motor variable	35, 45, 60, 150 s
	Noise level, motor	35 dB(A)
	Shaft Diameter	8x8 mm form fit
	Position indication	Mechanically, 3065 mm stroke
Safety data	Degree of protection IEC/EN	IP54
	Degree of protection NEMA/UL	NEMA 2
	Enclosure	UL Enclosure Type 2
	Agency Listing	cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2014/30/EU and 2014/35/EU; Listed to UL 2043 - suitable for use in air plenums per Section 300.22(c) of the NEC and Section 602.2 of the IMC
	Quality Standard	ISO 9001
	Ambient temperature	-22122°F [-3050°C]
	Storage temperature	-40176°F [-4080°C]
	Ambient humidity	Max. 95% RH, non-condensing
	Servicing	maintenance-free
Weight	Weight	0.64 lb [0.29 kg]
Materials	Housing material	UL94-5VA



Product features

Application

For On/Off and floating point control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications.

The actuator is mounted directly to a damper shaft from 1/4" up to 5/8" in diameter by means of its standard universal clamp. Shafts up to 3/4" diameter can be accommodated by an accessory clamp.

Operation

The actuator is not provided with and does not require any limit switches, but is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement.

The LMX series provides 95° of rotation and a visual indicator which indicates position of the actuator. When reaching the damper or actuator end position, the actuator automatically stops. The gears can be disengaged with manual release on the actuator cover.

The LMX120-3 actuators use a sensorless brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in holding mode.

Add-on auxiliary switches or feedback potentiometers are easily fastened directly onto the actuator body for signaling and switching functions.

Typical specification

Proportional control damper actuators shall be electronic direct-coupled type, which require no crank arm and linkage. Actuators must provide proportional damper control in response to a 2 to 10 VDC or, with the addition of a 500 Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. Actuators shall have brushless DC motor technology and be protected from overload at all angles of rotation. Actuators shall have reversing switch and manual override on the cover. Run time shall be constant and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position indication. Actuators shall be cULus listed, have a 5-year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

Accessories

Electrical accessories	Description	Туре
	Auxiliary switch 2 x SPDT add-on	S2A

Electrical installation

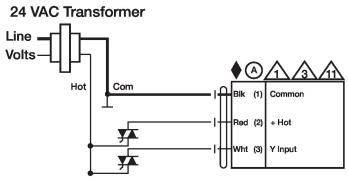
A Actuators with appliance cables are numbered.

Provide overload protection and disconnect as required.

Actuators may also be powered by DC 24 V.

Actuators Hot wire must be connected to the control board common. Only connect common to neg. (-) leg of control circuits. Terminal models (-T) have no-feedback.

 ${f X}$ Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.



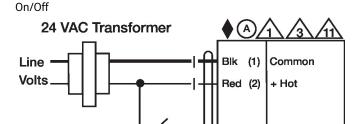
Floating Point - Triac Source

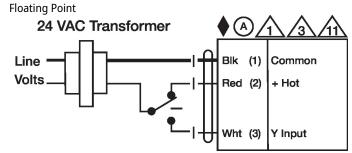
Y Input

Wht (3)

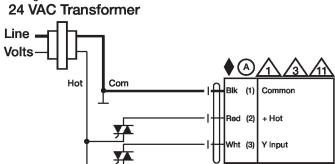


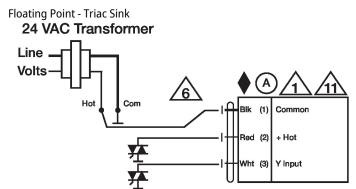
Wiring diagrams





Floating Point - Triac Source





Dimensions

