**Technical data sheet** 

LMX24-SR-F

Modulating, Non-Spring Return, 24 V, for DC 2...10 V or 4...20 mA







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Nominal voltage frequency 50/60 Hz  Power consumption in operation 1.5 W	
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. over consumption in operation	
Power consumption in rest position 0.4 W	
Transformer sizing 3 VA (class 2 power source	ce)
Electrical Connection 18 GA plenum cable with connector, degree of pro 3 ft [1 m] 10 ft [3 m] and	otection NEMA 2 / IP54,
Overload Protection electronic throughout 0	95° rotation
Functional data	
Position feedback U 210 V	
Position feedback U note Max. 0.5 mA	
Direction of motion motor selectable with switch 0/	1
Manual override external push button	
Angle of rotation Max. 95°	
Angle of rotation note adjustable with mechanic	cal stop
Running Time (Motor) 95 s / 90°	
Running time motor note constant, independent of	f load
Running time motor variable 35, 45, 60, 150 s	
Noise level, motor 35 dB(A)	
Shaft Diameter 8x8 mm form fit	
Position indication Mechanically, 3065 mm	n stroke
Safety data Degree of protection IEC/EN IP54	
Degree of protection NEMA/UL NEMA 2	
Enclosure UL Enclosure Type 2	
Agency Listing cULus acc. to UL60730-1/ E60730-1:02, CE acc. to 2 2014/35/EU; Listed to UL in air plenums per Sectio and Section 602.2 of the	014/30/EU and 2043 - suitable for use on 300.22(c) of the NEC
Quality Standard ISO 9001	
Ambient temperature -22122°F [-3050°C]	
Storage temperature -40176°F [-4080°C]	
Ambient humidity Max. 95% RH, non-conde	ensing
Servicing maintenance-free	

UL94-5VA

Materials

Housing material



#### **Product features**

# **Application**

For On/Off and floating point control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications.

The actuator is mounted directly to a damper shaft from 1/4" up to 5/8" in diameter by means of its standard universal clamp. Shafts up to 3/4" diameter can be accommodated by an accessory clamp.

#### Operation

The actuator is not provided with and does not require any limit switches, but is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement.

The LMB series provides 95° of rotation and a visual indicator indicates position of the actuator. When reaching the damper or actuator end position, the actuator automatically stops. The gears can be manually disengaged with a button on the actuator cover.

The LMB24-SR... actuators use a sensorless brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in holding mode.

Add-on auxiliary switches or feedback potentiometers are easily fastened directly onto the actuator body for signaling and switching functions.

## Typical specification

Proportional control damper actuators shall be electronic direct-coupled type, which require no crank arm and linkage and be capable of direct mounting to a shaft from 1/4" to 5/8" diameter. Actuators must provide control in response to a control input from an electronic controller or positioner. Actuators shall have brushless DC motor technology and be protected from overload at all angles of rotation. Actuators shall have reversing switch and manual override on the cover. Run time shall be constant and independent of torque. Actuators shall be cULus listed, have a 5-year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

## **Accessories**

Electrical accessories	Description	Туре
	Auxiliary switch 2 x SPDT add-on	S2A

### **Electrical installation**

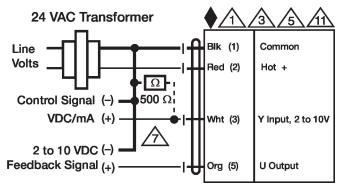
A Provide overload protection and disconnect as required.

Actuators may also be powered by DC 24 V.

Only connect common to negative (-) leg of control circuits.

 $\Lambda$  A 500  $\Omega$  resistor (ZG-R01) converts the 4...20 mA control signal to 2...10 V.

Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.



2...10 V / 4...20 mA Control



# **Dimensions**

