Modulating, Non-Spring Return, 24 V, 0 to 135  $\Omega$  Input











nical data		
Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Power consumption in operation	3.5 W
	Power consumption in rest position	1.3 W
	Transformer sizing	6 VA (class 2 power source)
	Electrical Connection	18 GA plenum cable with 1/2" conduit connector, degree of protection NEMA 2 / IP54 3 ft [1 m] 10 ft [3 m] and 16ft [5 m]
	Overload Protection	electronic throughout 095° rotation
Functional data	Torque motor	90 in-lb [10 Nm]
	Operating range Y	0135 Ω
	Operating range Y note	Honeywell Electronic Series 90, input 0135 $\Omega$
	Position feedback U	210 V
	Position feedback U note	Max. 0.5 mA
	Position feedback U variable	VDC variable
	Direction of motion motor	selectable with switch 0/1
	Manual override	external push button
	Angle of rotation	Max. 95°
	Angle of rotation note	adjustable with mechanical stop
	Running Time (Motor)	150 s / 90°
	Running time motor variable	45170 s
	Noise level, motor	45 dB(A)
	Shaft Diameter	1/21.05" round, centers on 1/2" and 3/4" with insert, 1.05" without insert
	Position indication	Mechanically, 3065 mm stroke
Safety data	Degree of protection IEC/EN	IP54
·	Degree of protection NEMA/UL	NEMA 2
	Enclosure	UL Enclosure Type 2
	Agency Listing	cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2014/30/EU and 2014/35/EU; Listed to UL 2043 - suitable for use in air plenums per Section 300.22(c) of the NEC and Section 602.2 of the IMC
	Quality Standard	ISO 9001
	Ambient temperature	-22122°F [-3050°C]
	Storage temperature	-40176°F [-4080°C]
	Ambient humidity	Max. 95% RH, non-condensing

1.2 lb [0.55 kg]

Weight Weight



Materials Housing material UL94-5VA

Footnotes †Rated Impulse Voltage 800V, Type action 1, Control Pollution Degree 3.

#### **Product features**

#### **Application**

For proportional modulation of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications.

The actuator is mounted directly to a damper shaft up to 1.05" in diameter by means of its universal clamp. A crank arm and several mounting brackets are available for applications where the actuator cannot be direct coupled to the damper shaft.

The default parameters for 0 to  $135\Omega$  input applications of the ...MFT95 actuator are assigned during manufacturing. If necessary, custom versions of the actuators can be ordered. The parameters can be changed by two means: pre-set and custom configurations from Belimo or on-site configurations using the Belimo PC-Tool software.

### Operation

The actuator is not provided with and does not require any limit switches, but is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement.

The actuator provides 95° of rotation and a visual indicator indicates position of the actuator. When reaching the damper or actuator end position, the actuator automatically stops. The gears can be manually disengaged with a button on the actuator cover.

The actuators use a brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in holding mode.

Add-on auxiliary switches or feedback potentiometers are easily fastened directly onto the actuator body for signaling and switching functions.

For low ambient temperatures, the optional supplemental (-H) Heater add-on is available.

### Typical specification

Proportional control damper actuators shall be electronic type, with integrated linear stroking arm. Actuators must provide proportional damper control in response to a 2 to 10 VDC or, with the addition of a  $500\Omega$  resistor, a 4 to 20 mA control input from an electronic controller or positioner. Actuators shall have brushless DC motor technology and be protected from overload at all angles of rotation. Actuators shall have reversing switch and manual override on the cover. Run time shall be constant and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position indication. Actuators shall be cULus listed, have a 5-year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

## Accessories

Electrical accessories	Description	Туре
	Auxiliary switch 1 x SPDT add-on	S1A
	Auxiliary switch 2 x SPDT add-on	S2A
	Feedback potentiometer 10 kΩ add-on, grey	P10000A GR
	Feedback potentiometer 1 k $\Omega$ add-on, grey	P1000A GR
	Feedback potentiometer 140 $\Omega$ add-on, grey	P140A GR
	Feedback potentiometer 2.8 kΩ add-on, grey	P2800A GR
	Feedback potentiometer 5 k $\Omega$ add-on, grey	P5000A GR
	Feedback potentiometer 500 $\Omega$ add-on, grey	P500A GR
	Battery backup system, for non-spring return models	NSV24 US
	Transformer, AC 120 V to AC 24 V, 40 VA	ZG-X40



# Technical data sheet NMX24-MFT95

#### Mechanical accessories

Description	Туре
Shaft clamp reversible, clamping range Ø820 mm	K-NA
17" Mounting Bracket for AF,NF,GM,AM,SM	ZG-100
Mounting Bracket: AF,NF,LF,GM,AM,NM,SM	ZG-101
Mounting Bracket: GM,AM,SM	ZG-103
Mounting Bracket: GM,AM,SM	ZG-104
Mounting kit for linkage operation for flat installation	ZG-NMA
Shaft extension 240 mm Ø20 mm for damper shaft Ø 822.7 mm	AV8-25
Shaft extension for 1/2" diameter shafts (3.8" L).	ZG-NMSA-1
Weather shield 330x203x152 mm [13x8x6"] (LxBxH)	ZS-100
Weather shield 406x213x102 mm [16x8-3/8x4"] (LxWxH)	ZS-150
Wrench 0.32 in and 0.39 in [8 mm and 10 mm]	TOOL-06
	ZG-JSL

## **Electrical installation**

A Provide overload protection and disconnect as required.

Actuators may also be powered by DC 24 V.

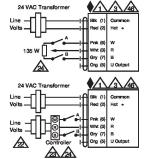
 $\sqrt{22}$  Actuators and controller must have separate transformers.

23 Consult controller instruction data for more detailed information.

Resistor value depends on the type of controller and the number of actuators. No resistor is used for one actuator. Honeywell® resistor kits may also be used.

25 To reverse control rotation, use the reversing switch.

Actuators may be controlled in parallel. Current draw and input impedance must be observed.



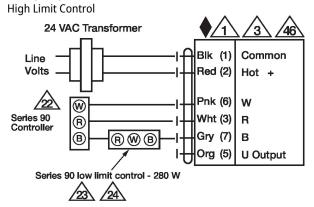
Demper Open

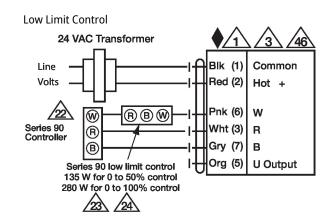
Demper Closed

The direction of rotation switch is set so that the fall safe position and the position of the demper is closed with no signal at wive R.

Typical and Override Control

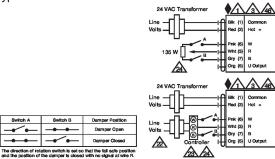
### Wiring diagrams



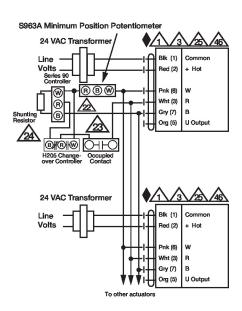


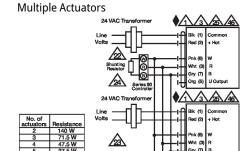


## Typical and Override Control



Multiple Actuators with Minimum Position Potentiometer







# **Dimensions**

- Ø 1/2" to 1.05 [12.7 to 26.67]
- 2/5" to 1.05" [10 to 26.67]

