


5-year warranty

## Technical data

| Functional data | Mounting Position | $90^{\circ}$ to $180^{\circ}$ |
| ---: | :--- | :--- |
| Safety data | Ambient temperature | $-22 \ldots 122^{\circ} \mathrm{F}\left[-30 \ldots . .50^{\circ} \mathrm{C}\right]$ |
| Materials | Storage temperature | $-40 \ldots 176^{\circ} \mathrm{F}\left[-40 \ldots 80^{\circ} \mathrm{C}\right]$ |
|  | Housing material | galvanized steel |
| Suitable actuators | Frame, plate, base | steel |
|  | Bearing | galanized steel |
|  |  | GF Delrin |
|  |  | $\operatorname{AMB}(X)$ |
|  | Electronic fail-safe | $\operatorname{GMB}(X)$ |
|  |  | $\operatorname{NMB}(X)$ |

* ZG-121 adapter must be used with EF. ** GM/GK not for use with 1/2" shafts. *** K6-1 clamp must be used with LF. For close-off pressure reference Select Pro or Retrofit Technical Documentation.
For close-off pressure reference Select Pro or retrofit technical documentation.


## Product features

Default/Configuration The ZG-JSL linkage can also be configured by moving the anti-rotation plate $90^{\circ}$ for space-saving applications. See mounting configurations below. The ZG-JSLA will have a factory mounted actuator on the linkage in the vertical position only.

Application The ZG-JSL jackshaft linkage is designed to easily attach to any part of a jackshaft and allow easy installation of select Belimo actuators. The unique open ended design and clamp insert allows the ZG-JSL to be used with any jackshaft from $1 / 2^{\prime \prime}$ to $3 / 4^{\prime \prime}$ in diameter. Removal of the insert will allow the linkage to attach to a maximum shaft diameter of $1.05^{\prime \prime}$. Changing the antirotation plate will allow various actuators to be mounted.

Operation The $3 / 4^{\prime \prime}$ diameter built-in steel shaft allows direct coupling to the Belimo series actuators in the chart below. There is a torque reduction when using the ZG-JSL linkage. Verify application requirements before use.

Flow/Mounting details



Modulating, Spring Return, 24 V , Multi-Function Technology®

Proportional, Spring Return, 24 V Multi-Function Technology, Torque min. $180 \mathrm{in}-\mathrm{lb}$, Control 2 to 10 VDC (DEFAULT), Feedback 2 to 10 VDC (DEFAULT)



## Technical data

| Electrical data | Nominal voltage | AC/DC 24 V |
| :---: | :---: | :---: |
|  | Nominal voltage frequency | 50/60 Hz |
|  | Power consumption in operation | 7.5 W |
|  | Power consumption in rest position | 3 W |
|  | Transformer sizing | 10 VA (class 2 power source) |
|  | Auxiliary switch | $2 \times$ SPDT, 3 A resistive ( 0.5 A inductive) @ AC 250 V , one set at $10^{\circ}$, one adjustable 10 ... $90^{\circ}$ |
|  | Switching capacity auxiliary switch | 3 A resistive (0.5 A inductive) @ AC 250 V |
|  | Electrical Connection | (2) 18 GA appliance cables with or without $1 / 2^{\prime \prime}$ conduit connectors, $3 \mathrm{ft}[1 \mathrm{~m}$ ], $10 \mathrm{ft}[3 \mathrm{~m}]$ or $16 \mathrm{ft}[5$ $\mathrm{m}]$ |
|  | Overload Protection | electronic throughout $0 . . .95^{\circ}$ rotation |
|  | Electrical Protection | actuators are double insulated |
| Functional data | Torque motor | 180 in-lb [20 Nm] |
|  | Operating range Y | 2...10 V |
|  | Operating range Y note | $4 . . .20 \mathrm{~mA} \mathrm{w/} \mathrm{ZG-R01} \mathrm{( } 500 \Omega, 1 / 4 \mathrm{~W}$ resistor) |
|  | Input Impedance | $100 \mathrm{k} \Omega$ for $2 . . .10 \mathrm{~V}(0.1 \mathrm{~mA}), 500 \Omega$ for $4 . . .20 \mathrm{~mA}$, $1500 \Omega$ for PWM, On/Off and Floating point |
|  | Operating range $Y$ variable | Start point 0.5... 30 V |
|  |  | End point 2.5... 32 V |
|  | Options positioning signal | variable (VDC, PWM, on/off, floating point) |
|  | Position feedback U | 2...10 V |
|  | Position feedback U note | Max. 0.5 mA |
|  | Position feedback U variable | VDC variable |
|  | Direction of motion motor | selectable with switch 0/1 |
|  | Direction of motion fail-safe | reversible with $\mathrm{cw} / \mathrm{ccw}$ mounting |
|  | Manual override | 5 mm hex crank (3/16" Allen), supplied |
|  | Angle of rotation | $95^{\circ}$, adjustable with mechanical end stop, $35 . . .95^{\circ}$ |
|  | Angle of rotation note | adjustable with mechanical end stop, 35...95 ${ }^{\circ}$ |
|  | Running Time (Motor) | default 150 s , variable $70 . . .220 \mathrm{~s}$ |
|  | Running time motor variable | $70 . .220 \mathrm{~s}$ |
|  | Running time fail-safe | <20 s @ -4...122 ${ }^{\circ} \mathrm{F}\left[-20 . . .50^{\circ} \mathrm{C}\right]$, <60 s @ -22 ${ }^{\circ} \mathrm{F}$ [ $\left.-30^{\circ} \mathrm{C}\right]$ |
|  | Angle of rotation adaptation | off (default) |
|  | Override control | MIN ( minimum position) $=0 \%$ |
|  |  | MID (intermediate position) $=50 \%$ |
|  |  | $\operatorname{MAX}$ (maximum position) $=100 \%$ |
|  | Noise level, motor | 40 dB (A) |
|  | Noise level, fail-safe | $62 \mathrm{~dB}(\mathrm{~A})$ |
|  | Shaft Diameter | $1 / 2 . . .1 .05$ " round, centers on $1 / 2^{\prime \prime}$ and $3 / 4^{"}$ with insert, 1.05 " without insert |


|  | Position indication | Mechanical |
| :---: | :---: | :---: |
| Safety data | Degree of protection IEC/EN | IP54 |
|  | Degree of protection NEMA/UL | NEMA 2 UL Enclosure Type 2 |
|  | Agency Listing | cULus acc. to UL60730-1A/-2-14, CAN/CSA |
|  |  | E60730-1:02, CE acc. to 2014/30/EU and 2014/35/ |
|  |  | EU; Listed to UL 2043 - suitable for use in air plenums per Section 300.22(c) of the NEC and |
|  |  | Section 602.2 of the IMC |
|  | Quality Standard | ISO 9001 |
|  | Ambient temperature | $-22 . .122^{\circ} \mathrm{F}\left[-30 . . .50^{\circ} \mathrm{C}\right]$ |
|  | Storage temperature | $-40 . .176^{\circ} \mathrm{F}\left[-40 . . .80^{\circ} \mathrm{C}\right]$ |
|  | Ambient humidity | max. 95\% r.H., non-condensing |
|  | Servicing | maintenance-free |
| Weight | Weight | 4.2 lb [1.9 kg] |
| Materials | Housing material | Galvanized steel and plastic housing |

## Product features

## Default/Configuration

Default parameters for 2 to 10 VDC applications of the AF..-MFT actuator are assigned during manufacturing. If required, custom versions of the actuator can be ordered. The parameters are variable and can be changed by three means: Factory pre-set or custom configuration, set by the customer using PC-Tool software or the handheld ZTH US.

Application For fail-safe, modulating control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. A feedback signal is provided for position indication for master-slave applications. Two AF's can be piggybacked for torque loads to max. $360 \mathrm{in}-\mathrm{lb}$. Minimum 3/4" diameter shaft. OR Maximum of three AF's can be piggybacked for torque loads to max. 432 in-lb. Minimum 3/4" diameter shaft. Master-Slave wiring for either configuration. Actuators must be mechanically linked.
When not mechanically linked, actuators must be wired in parallel.
Operation The AF..24-MFT actuator provides $95^{\circ}$ of rotation and is provided with a graduated position indicator showing $0^{\circ}$ to $95^{\circ}$. The actuator will synchronize the $0^{\circ}$ mechanical stop or the physical damper or valve mechanical stop and use this point for its zero position during normal control operations. A unique manual override allows the setting of any actuator position within its $95^{\circ}$ of rotation with no power applied. This mechanism can be released physically by the use of a crank supplied with the actuator. When power is applied the manual override is released and the actuator drives toward the fail-safe position. The actuator uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuators's exact position. The ASIC monitors and controls the brushless DC motor's rotation and provides a Digital Rotation Sensing (DRS) function to prevent damage to the actuator in a stall condition. The position feedback signal is generated without the need for mechanical feedback potentiometers using DRS. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. The AF..24-MFT is mounted directly to control shafts up to 1.05 " diameter by means of its universal clamp and anti-rotation bracket. A crank arm and several mounting brackets are available for damper applications where the actuator cannot be direct coupled to the damper shaft. The spring return system provides minimum specified torque to the application during a power interruption. The AF..24-MFT actuator is shipped at $5^{\circ}\left(5^{\circ}\right.$ from full fail-safe) to provide automatic compression against damper gaskets for tight shut-off.

Typical specification Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a 1.05" diameter. The actuator must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a $500 \Omega$ resistor, a 4 to 20 mA control input from an electronic controller or positioner. The actuators must be designed so that they may be used for either clockwise or counter clockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback or master slave applications. Actuators with auxiliary switches must be constructed to meet the requirements for Double Insulation so an electrical ground is not required to meet agency listings. Actuators shall be cULus listed and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

Factory settings Default parameters for 2 to 10 VDC applications of the AF..-MFT actuator are assigned during manufacturing. If required, custom versions of the actuator can be ordered. The parameters are variable and can be changed by three means: Factory pre-set or custom configuration, set by the customer using PC-Tool software or the handheld ZTH US.

## Accessories

| Gateways | Description | Type |
| :---: | :---: | :---: |
|  | Gateway MP to BACnet MS/TP | UK24BAC |
|  | Gateway MP to LonWorks | UK24LON |
|  | Gateway MP to Modbus RTU | UK24MOD |
| Electrical accessories | Description | Type |
|  | DC Voltage Input Rescaling Module | IRM-100 |
|  | Belimo PC-Tool, Software for adjustments and diagnostics | MFT-P |
|  | Auxiliary switch, mercury-free | P475 |
|  | Auxiliary switch, mercury-free | P475-1 |
|  | Signal Siumlator, Power supply AC 230 V | PS-100 |
|  | Convert Pulse Width Modulated Signal to a 2... 10 V Signal for Belimo Proportional Actuators | PTA-250 |
|  | Positioner for wall mounting | SGA24 |
|  | Positioner for front-panel mounting | SGF24 |
|  | Cable Conduit Connector 1/2" | TF-CC US |
|  | Gateway MP to BACnet MS/TP | UK24BAC |
|  | Gateway MP to LonWorks | UK24LON |
|  | Gateway MP to Modbus RTU | UK24MOD |
|  | Resistor, $500 \Omega, 1 / 4$ " wire resistor with 6 " pigtail wires | ZG-R01 |
|  | Resistor Kit, 50\% voltage divider | ZG-R02 |
|  | Mounting plate for SGF. | ZG-SGF |
|  | Transformer, AC 120 V to $\mathrm{AC} 24 \mathrm{~V}, 40 \mathrm{VA}$ | ZG-X40 |
|  | Connection cable $16 \mathrm{ft}[5 \mathrm{~m}$ ], A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal | ZK2-GEN |
|  | Service Tool, with ZIP-USB function, for parametrisable and communicative Belimo actuators, VAV controller and HVAC performance devices | ZTH US |
| Mechanical accessories | Description | Type |
|  | Anti-rotation bracket, for AF / NF | AF-P |
|  | Shaft extension 240 mm Ø 20 mm for damper shaft $\emptyset 8 . . .22 .7 \mathrm{~mm}$ | AV8-25 |
|  | End stop indicator | IND-AFB |
|  | Shaft clamp reversible, for central mounting, for damper shafts ø12.7 / 19.0 / 25.4 mm | K7-2 |
|  | Ball joint suitable for damper crank arm KH8 / KH10 | KG10A |
|  | Ball joint suitable for damper crank arm KH8 | KG8 |
|  | Actuator arm, for 3/4" shafts, clamping range $\emptyset 10 . . .22 \mathrm{~mm}$, Slot width 8.2 mm | KH-AFB |
|  | Damper crank arm Slot width 8.2 mm , clamping range $\varnothing 14 \ldots . .25 \mathrm{~mm}$ | KH10 |
|  | Damper crank arm Slot width 8.2 mm , for $\varnothing 1.05{ }^{\prime \prime}$ | KH12 |
|  | Damper crank arm Slot width 8.2 mm , clamping range $\emptyset 10 . . .18 \mathrm{~mm}$ | KH8 |
|  | Push rod for KG10A ball joint ( $36^{\prime \prime} \mathrm{L}, 3 / 8^{\prime \prime}$ diameter). | SH10 |
|  | Push rod for KG6 \& KG8 ball joints ( 36 " L, 5/16" diameter). | SH8 |
|  | Wrench 8 mm and 10 mm | TOOL-06 |
|  | Retrofit clip | Z-AF |
|  | Base plate extension | Z-SF |

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    17" Mounting Bracket for AF,NF,GM,AM,SM ZG-100
    Mounting Bracket: AF,NF,LF,GM,AM,NM,SM ZG-101
    Dual actuator mounting bracket. ZG-102
    Mounting Bracket: ZS-260 Right Angle ZG-109
    Linkage kit ZG-110
    Mounting bracket ZG-118
    for AF / NF
    Jackshaft mounting bracket. ZG-120
    Mounting kit for linkage operation for flat and side installation ZG-AFB
    Mounting kit for foot mount installation ZG-AFB118
    Damper clip for damper blade, 3.5" width. ZG-DC1
    Damper clip for damper blade, 6" width. ZG-DC2
    1" diameter jackshaft adaptor (11" L). ZG-SA-1
    1-5/16" diameter jackshaft adaptor (12" L). ZG-JSA-2
    1.05" diameter jackshaft adaptor (12" L). ZG-JSA-3
    Weather shield 13x8x6" [330x203x152 mm](LxWxH) ZS-100
    Base Plate, for ZS-100 ZS-101
    Weather shield 16\times8-3/8\times4" [406\times213x102 mm] (LxWxH) ZS-150
    Explosion Proof Housing 16x10x6.435" [406x254x164 mm] (LxWxH), UL and CSA, ZS-260
    Class I, Zone 1&2, Groups B, C, D, (NEMA 7), Class III, Hazardous (classified)
    Locations
    Weather shield 17-1/4\times8-3/4\times5-1/2" [438\times222x140 mm] (LxWxH), NEMA 4X, with ZS-300
    mounting brackets
    Weather shield 17-1/4x8-3/4x5-1/2" [438\times222x140 mm] (LxWxH), NEMA 4X, with ZS-300-5
    mounting brackets
    Shaft extension 1/2" ZS-300-C1
    Shaft extension 3/4" ZS-300-C2
    Shaft extension 1" ZS-300-C3
Service tools Description Type
    Connection cable 10 ft [3 m], A: RJ11 6/4 ZTH EU, B: 3-pin Weidmüller and supply ZK4-GEN
    connection
    Service Tool, with ZIP-USB function, for parametrisable and communicative ZTH US
    Belimo actuators, VAV controller and HVAC performance devices
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## Warning! Live Electrical Components!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.
Meets cULus requirements without the need of an electrical ground connection.
Apply only AC line voltage or only UL-Class 2 voltage to the terminals of auxiliary switches. Mixed or combined operation of line voltage/safety extra low voltage is not allowed.Actuators with appliance cables are numbered.
Provide overload protection and disconnect as required.
Actuators may also be powered by 24 VDC.
Two built-in auxiliary switches (2x SPDT), for end position indication, interlock control, fan startup, etc.
5 Only connect common to negative (-) leg of control circuits.
A $500 \Omega$ resistor (ZG-R01) converts the $4 . . .20 \mathrm{~mA}$ control signal to $2 . . .10 \mathrm{~V}$.
8 Control signal may be pulsed from either the Hot (Source) or Common (Sink) 24 V line.
For triac sink the Common connection from the actuator must be connected to the Hot connection of the controller. Position feedback cannot be used with a triac sink controller; the actuator internal common reference is not compatible.
12 IN4004 or IN4007 diode. (IN4007 supplied, Belimo part number 40155).
Actuators may be controlled in parallel when not mechanically linked. Current draw and input impedance must be observed.
Master-Slave wiring required for piggy-back applications when mechanically linked. Feedback from Master to control input(s) of Slave(s).


On/Off


VDC/mA Control


Override Control


Floating Point

PWM Control


Master - Slave


- 4 4


Auxiliary Switches

## Dimensions



