





Technical data					
Functional data	Mounting Position	90° to 180°			
Safety data	Ambient temperature	-22122°F [-3050°C]			
	Storage temperature	-40176°F [-4080°C]			
Materials	Housing material	galvanized steel			
	Stem	steel			
	Frame, plate, base	galanized steel			
	Bearing	GF Delrin			
Suitable actuators	Non-Spring	AMB(X)			
		GMB(X)			
		NMB(X)			
	Electronic fail-safe	NKQB(X)			

^{*} ZG-121 adapter must be used with EF. ** GM/GK not for use with 1/2" shafts. *** K6-1 clamp must be used with LF. For close-off pressure reference Select Pro or Retrofit Technical Documentation.

For close-off pressure reference Select Pro or retrofit technical documentation.

Product features

Default/Configuration

The ZG-JSL linkage can also be configured by moving the anti-rotation plate 90° for space-saving applications. See mounting configurations below. The ZG-JSLA will have a factory mounted actuator on the linkage in the vertical position only.

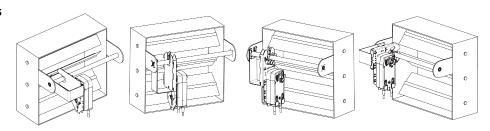
Application

The ZG-JSL jackshaft linkage is designed to easily attach to any part of a jackshaft and allow easy installation of select Belimo actuators. The unique open ended design and clamp insert allows the ZG-JSL to be used with any jackshaft from ½" to ¾" in diameter. Removal of the insert will allow the linkage to attach to a maximum shaft diameter of 1.05". Changing the antirotation plate will allow various actuators to be mounted.

Operation

The $\frac{3}{4}$ " diameter built-in steel shaft allows direct coupling to the Belimo series actuators in the chart below. There is a torque reduction when using the ZG-JSL linkage. Verify application requirements before use.

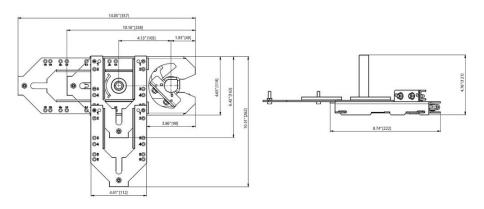
Flow/Mounting details



Dimensions



Dimensional drawings





Modulating, Spring Return, 24 V, Multi-Function Technology®

Proportional, Spring Return, 24 V Multi-Function Technology, Torque min. 180 in-lb, Control 2 to 10 VDC (DEFAULT), Feedback 2 to 10 VDC (DEFAULT)

Technical data sheet











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Electrical data	Nominal voltage	AC/DC 24 V	
	Nominal voltage frequency	50/60 Hz	
	Power consumption in operation	7.5 W	
	Power consumption in rest position	3 W	
	Transformer sizing	10 VA (class 2 power source)	
	Electrical Connection	18 GA appliance or plenum cables, 3 ft [1 m], 10 ft [3 m] or 16ft [5 m], with or without 1/2" conduit	
	0 1 10 11	connector	
	Overload Protection	electronic throughout 095° rotation	
	Electrical Protection	actuators are double insulated	
Functional data	Torque motor	180 in-lb [20 Nm]	
	Operating range Y	210 V	
	Operating range Y note	420 mA w/ ZG-R01 (500 Ω, 1/4 W resistor)	
	Input Impedance	100 k Ω for 210 V (0.1 mA), 500 Ω for 420 mA, 1500 Ω for PWM, On/Off and Floating point	
	Operating range Y variable	Start point 0.530 V End point 2.532 V	
	Options positioning signal	variable (VDC, PWM, on/off, floating point)	
	Position feedback U	210 V	
	Position feedback U note	Max. 0.5 mA	
	Position feedback U variable	VDC variable	
	Direction of motion motor	selectable with switch 0/1	
	Direction of motion fail-safe	reversible with cw/ccw mounting	
	Manual override	5 mm hex crank (3/16" Allen), supplied	
	Angle of rotation	95°, adjustable with mechanical end stop, 3595°	
	Angle of rotation note	adjustable with mechanical end stop, 3595°	
	Running Time (Motor)	default 150 s, variable 70220 s	
	Running time motor variable	70220 s	
	Running time fail-safe	<20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]	
	Angle of rotation adaptation	off (default)	
	Override control	MIN (minimum position) = 0% MID (intermediate position) = 50% MAX (maximum position) = 100%	
	Noise level, motor	40 dB(A)	
	Noise level, fail-safe	62 dB(A)	
	Shaft Diameter	1/21.05" round, centers on 1/2" and 3/4" with insert, 1.05" without insert	
	Position indication	Mechanical	
Safety data	Degree of protection IEC/EN	IP54	

AFX24-MFT • en-us • 2021-02-04 • Subject to change



Technical data sheet	AFX24-MFT	
Degree of protection NEMA/UL	NEMA 2 UL Enclosure Type 2	
Agency Listing	cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2014/30/EU and 2014/35/ EU; Listed to UL 2043 - suitable for use in air plenums per Section 300.22(c) of the NEC and Section 602.2 of the IMC	
Quality Standard	ISO 9001	
Ambient temperature	-22122°F [-3050°C]	
Storage temperature	-40176°F [-4080°C]	
Ambient humidity	max. 95% r.H., non-condensing	
Servicing	maintenance-free	
Weight	4.1 lb [1.9 kg]	
Housing material	Galvanized steel and plastic housing	

Product features

Default/Configuration

Default parameters for 2 to 10 VDC applications of the AF..-MFT actuator are assigned during manufacturing. If required, custom versions of the actuator can be ordered. The parameters are variable and can be changed by three means: Factory pre-set or custom configuration, set by the customer using PC-Tool software or the handheld ZTH US.

Application

Weight

Materials

For fail-safe, modulating control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. A feedback signal is provided for position indication for master-slave applications. Two AF's can be piggybacked for torque loads to max. 360 in-lb. Minimum 3/4" diameter shaft. OR Maximum of three AF's can be piggybacked for torque loads to max. 432 in-lb. Minimum 3/4" diameter shaft. Master-Slave wiring for either configuration. Actuators must be mechanically linked.

When not mechanically linked, actuators must be wired in parallel.

Operation

The AF..24-MFT actuator provides 95° of rotation and is provided with a graduated position indicator showing 0° to 95°. The actuator will synchronize the 0° mechanical stop or the physical damper or valve mechanical stop and use this point for its zero position during normal control operations. A unique manual override allows the setting of any actuator position within its 95° of rotation with no power applied. This mechanism can be released physically by the use of a crank supplied with the actuator. When power is applied the manual override is released and the actuator drives toward the fail-safe position. The actuator uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuators's exact position. The ASIC monitors and controls the brushless DC motor's rotation and provides a Digital Rotation Sensing (DRS) function to prevent damage to the actuator in a stall condition. The position feedback signal is generated without the need for mechanical feedback potentiometers using DRS. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. The AF..24-MFT is mounted directly to control shafts up to 1.05" diameter by means of its universal clamp and anti-rotation bracket. A crank arm and several mounting brackets are available for damper applications where the actuator cannot be direct coupled to the damper shaft. The spring return system provides minimum specified torque to the application during a power interruption. The AF..24-MFT actuator is shipped at 5° (5° from full fail-safe) to provide automatic compression against damper gaskets for tight shut-off.

Typical specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a $1.05^{\prime\prime}$ diameter. The actuator must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a 500Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. The actuators must be designed so that they may be used for either clockwise or counter clockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback or master slave applications. Actuators with auxiliary switches must be constructed to meet the requirements for Double Insulation so an electrical ground is not required to meet agency listings. Actuators shall be cULus listed and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.







Factory settings

Default parameters for 2 to 10 VDC applications of the AF..-MFT actuator are assigned during manufacturing. If required, custom versions of the actuator can be ordered. The parameters are variable and can be changed by three means: Factory pre-set or custom configuration, set by the customer using PC-Tool software or the handheld ZTH US.

Accessories



	Technical data sheet	AFX24-MFT	
	1" diameter jackshaft adaptor (11" L).	ZG- SA-1	
	1-5/16" diameter jackshaft adaptor (12" L).	ZG-JSA-2	
	1.05" diameter jackshaft adaptor (12" L).	ZG-JSA-3	
	Weather shield 13x8x6" [330x203x152 mm] (LxWxH)	ZS-100	
	Base Plate, for ZS-100	ZS-101	
	Weather shield 16x8-3/8x4" [406x213x102 mm] (LxWxH)	ZS-150	
	Explosion Proof Housing 16x10x6.435" [406x254x164 mm] (LxWxH), UL and CSA,	ZS-260	
	Class I, Zone 1&2, Groups B, C, D, (NEMA 7), Class III, Hazardous (classified)		
	Locations		
	Weather shield 17-1/4x8-3/4x5-1/2" [438x222x140 mm] (LxWxH), NEMA 4X, with mounting brackets	ZS-300	
	Weather shield 17-1/4x8-3/4x5-1/2" [438x222x140 mm] (LxWxH), NEMA 4X, with mounting brackets	ZS-300-5	
	Shaft extension 1/2"	ZS-300-C1	
	Shaft extension 3/4"	ZS-300-C2	
	Shaft extension 1"	ZS-300-C3	
Service tools	Description	Туре	
	Connection cable 10 ft [3 m], A: RJ11 6/4 ZTH EU, B: 3-pin Weidmüller and supply connection	ZK4-GEN	
	Service Tool, with ZIP-USB function, for parametrisable and communicative Belimo actuators, VAV controller and HVAC performance devices	ZTH US	

Electrical installation



/ Warning! Live Electrical Components!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.

Meets cULus requirements without the need of an electrical ground connection.

Actuators with appliance cables are numbered.

Provide overload protection and disconnect as required.

Actuators may also be powered by 24 VDC.

Only connect common to negative (-) leg of control circuits.

 Λ A 500 Ω resistor (ZG-R01) converts the 4...20 mA control signal to 2...10 V.

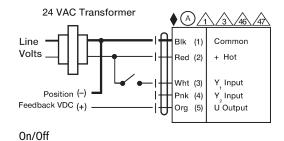
Control signal may be pulsed from either the Hot (Source) or Common (Sink) 24 V line.

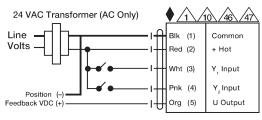
For triac sink the Common connection from the actuator must be connected to the Hot connection of the controller. Position feedback cannot be used with a triac sink controller; the actuator internal common reference is not compatible.

IN4004 or IN4007 diode. (IN4007 supplied, Belimo part number 40155).

Actuators may be controlled in parallel when not mechanically linked. Current draw and input impedance must be observed.

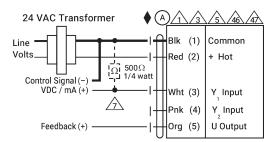
Master-Slave wiring required for piggy-back applications when mechanically linked. Feedback from Master to control input(s) of Slave(s).



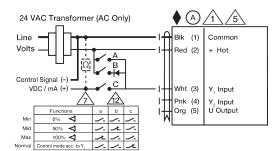


Floating Point

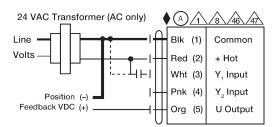




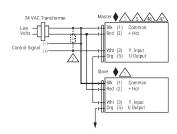
VDC/mA Control



Override Control



PWM Control



Master - Slave

Dimensions

Dimensional drawings

