

TM000FN TM020FN

TM060FN

TM080FN

RM000FN

RM020FN

RM060FN

RM080FN

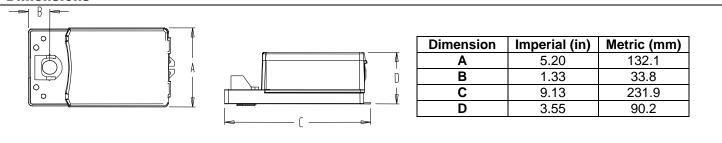


Features:

- Clutch for manual adjustments.
- Maintenance free.
- Position indicator.
- Control signal fully programmable.
- Brushless DC driven motor.
- Fail safe by *Enerdrive System*¹ (on model 060 & 080).
- Auxiliary switches (on model 020 & 080).

Fechnical Data	TM000FN	TM020FN	TM060FN	TM080FN	RM000FN	RM020FN	RM060FN	RM080FN
Auxiliary switches	No	Yes (2)	No	Yes (2)	No	Yes (2)	No	Yes (2)
Fail safe - Enerdrive	No		Yes		No		Yes	
Power consumption	25 VA		40 VA Peak, 25 VA		25 VA		40 VA Peak, 25 VA	
Torque	12	0 in.lb. [13.5 Nr	n] at rated volta] at rated voltage 24		40 in.lb. [27 Nm] at rated voltage		
Power supply	22 to 26 VAC or 28 to 32 Vdc							
Running time through 90°	15 to 20 sec torque dependant							
Feedback	4 to 20 mA or 2 to 10 Vdc adjustable							
Electrical connection	18 AWG [0.8 mm ²] minimum							
Inlet bushing	2 inlet bushing of 7/8 in [22.2 mm]							
Control signal	Analog, Digital or PWM programmable (factory set with analog control signal)							
Angle of rotation	0 to 90 degrees, electronically adjustable (factory set with 90° stroke)							
Direction of rotation	Reversible, Clockwise (CW) or Counterclockwise (CCW) (factory set with CW direction)							
Operating temperature	0°F to 122°F [-18° C to 50°C]							
Storage temperature	-22°F to 122°F [-30° C to 50°C]							
Relative Humidity	5 to 95 % non condensing.							
Weight	4.5 lbs. [2 kg] 7 lbs. [3.2 kg]							

Dimensions



Caution

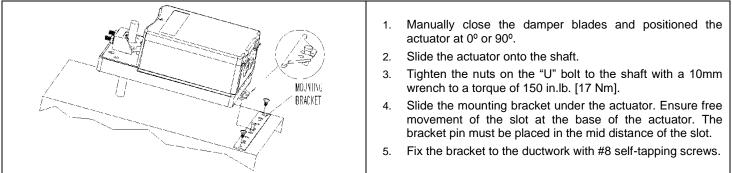
We strongly recommend that all Neptronic[®] products be wired to a separate transformer and that transformer shall service only Neptronic[®] products. This precaution will prevent interference with, and/or possible damage to incompatible equipment.

When multiple actuators are wired on a single transformer, polarity must be observed. Long wiring runs create voltage drop which may affect the actuator performance.

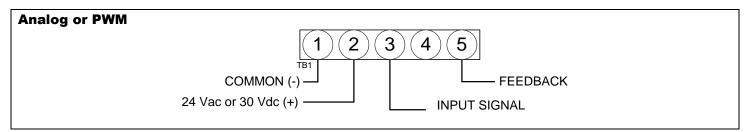
¹ Enerdrive System U.S.A. Patent #5,278,454

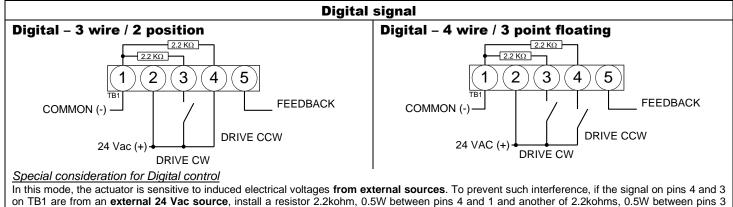
CE

Mechanical Installation



Wiring Diagrams





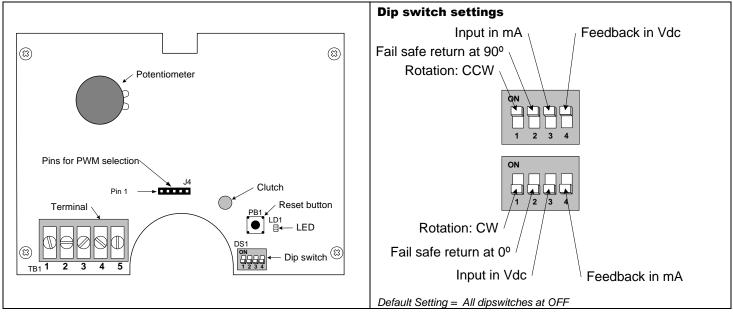
and 1 of TB1. These resistors are included.

Input Signal and Feedback setup

	Input Signal	Feedback		
Analog Mode	Input Signal is set with Dipswitch # 3 DS1-3 at OFF = 2 – 10Vdc (default setting) DS1-3 at ON = 4 – 20mA	Feedback is set with Dipswitch #4 DS1-4 at OFF = 4 – 20mA (default setting) DS1-4 at ON = 2 – 10Vdc		
Digital & PWM Mode	No Input Signal Setting DS1-3 MUST be at OFF			



PC Board



Stroke adjustment - No control signal change

- Apply power and, WAIT FOR LED TO BE OFF (around 10 seconds).
 Press and release the reset button to start the auto-stroke process.
 - Press and release the reset button to start the auto-stroke process. The LED should be illuminated.
 - First option:

The actuator will then travel in both directions to find its limit and position itself according to the demand. The LED will extinguish, the process is complete.

• Second option: When the desired start position is reached, press and release the reset button. The actuator will now go the end position. (you can also press and release the reset button when It's reaches the end position) The LED will extinguish, the process is complete.

Programming – Change of control signal & PWM pulse setting

- 1. Remove power and put all dip switches "OFF" (factory preset).
- 2. Apply power and, within 10 seconds, press and release the reset button. The LED should be blinking.
- 3. Select the control signal with dip switches:

	Digital or Analog Modes	PWM Mode
Move switch <u>No1</u> "ON" and then "OFF".	Digital (On/Off or 3 point floating)	5 sec. pulse (factory preset)
Move switch <u>No2</u> "ON" and then "OFF".	<u>Analog</u> (Default)	25 sec. pulse

Stroke adjustment

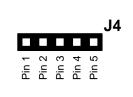
see the stroke adjustment section above.

Enabling or disabling PWM mode

- Remove power supply to actuator
 Install jumper between pin 3 & 4 of J4
- 3. Select the desired action using the dipswitches (DS1):

DS1-1	DS1-2	Action			
OFF	ON	Enable PWM Mode			
ON	OFF	Disable PWM Mode			

- 4. Re-apply power supply to actuator
- 5. Wait 5 seconds
- 6. Remove power supply to actuator
- 7. Remove jumper between pin 3 & 4 of J4, re-install it between pin 4 & 5.
- 8. Re-apply power supply to actuator *PWM is factory preset at 5 sec. pulse,*
 - refer to programming section above to change pulse setting



When not used for programming, jumper is placed between pin 4 & 5



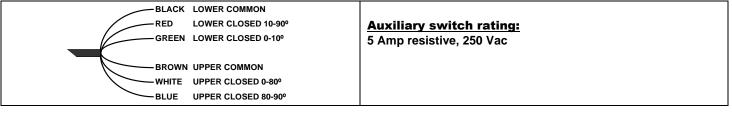
Zero and span calibration

This feature is applicable to analog control signal only.

- 1. Remove power and put all dip switches "OFF". (factory preset).
- 2. Apply power and, **within 10 seconds** press and **hold** the reset button until the LED blinks once. The Zero and span calibration process then start.
- 3. Release the reset button. The LED is now constantly illuminated.
- Apply new minimum voltage.
 It can be any value between 0 to 7 Vdc, with an external 0 to 10 volt supply (ex: MEP).
- 5. Press and release the reset button to memorize the new minimum voltage. The LED blinks.
- Apply new maximum voltage.
 It can be any value between 3 to 10 Vdc, this value should be greater than the new minimum value.
- 7. Press and release the reset button to memorize the new maximum voltage. The LED blinks. The Zero and span calibration process is complete.

Note: To reset zero and span to 2 to 10 Vdc (factory value). You just have to re-select the analog control signal mode, see Programming.

Wiring Diagrams for auxiliary switches (on model 020 & 080)



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