

Features:
TM100N

- Clutch for manual adjustments.

TM120N

- Maintenance free.
- Position indicator.

TM160N

- Control signal fully programmable.
- Brushless DC driven motor.
- Fail safe by EnerdriveSystem ${ }^{1}$
(on model 160 \& 180).
- Auxiliary switches
(on model 120 \& 180).

| Technical Data | TM100N | TM120N | TM160N | TM180N | RM100N | RM120N | RM160N | RM180N |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Auxiliary switches | No | Yes (2) | No | Yes (2) | No | Yes (2) | No | Yes (2) |
| Fail safe - Enerdrive | No |  | Yes |  | No |  | Yes |  |
| Power consumption | 20 VA |  | 45 VA Peak, 20 VA |  | 30 VA |  | 50 VA Peak, 30 VA |  |
| Torque | 180 in.lb. [20 Nm] at rated voltage |  |  |  | 360 in.lb. [40 Nm] at rated voltage |  |  |  |
| Running time through $90^{\circ}$ | 40 to 50 sec torque dependant |  |  |  |  |  |  |  |
| Power supply | 28 to 32 Vdc or 22 to $26 \mathrm{Vac}, 110$ to $130 \mathrm{Vac} 50 / 60 \mathrm{~Hz}$ |  |  |  |  |  |  |  |
| Feedback | 4 to 20 mA or 2 to 10 Vdc adjustable |  |  |  |  |  |  |  |
| Electrical connection | 18 AWG [ $0.8 \mathrm{~mm}^{2}$ ] minimum |  |  |  |  |  |  |  |
| Inlet bushing | 2 inlet bushing of $7 / 8$ in [ 22.2 mm ] |  |  |  |  |  |  |  |
| Control signal | Analog, Digital or PWM programmable (factory set with analog control signal) |  |  |  |  |  |  |  |
| Angle of rotation | 0 to 90 degrees, electronically adjustable (factory set with $90^{\circ}$ stroke) |  |  |  |  |  |  |  |
| Direction of rotation | Reversible, Clockwise (CW) or Counterclockwise (CCW) (factory set with CW direction) |  |  |  |  |  |  |  |
| Operating temperature | $0^{\circ} \mathrm{F}$ to $122^{\circ} \mathrm{F}$ [ $-18^{\circ} \mathrm{C}$ to $\left.50^{\circ} \mathrm{C}\right]$ |  |  |  |  |  |  |  |
| Storage temperature | $-22^{\circ} \mathrm{F}$ to $122^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right.$ to $\left.50^{\circ} \mathrm{C}\right]$ |  |  |  |  |  |  |  |
| Relative Humidity | 5 to $95 \%$ non condensing. |  |  |  |  |  |  |  |
| Weight | $5 \mathrm{lbs} .[2.3 \mathrm{~kg}$ ] |  |  |  | $8 \mathrm{lbs} .[3.5 \mathrm{~kg}$ ] |  |  |  |
| Warning: Do not press the clutch when actuator is powered |  |  |  |  |  |  |  |  |

## Dimensions



## Caution

[^0][^1]
## Mechanical Installation



## Wiring Diagrams

> Analog line voltage


## Analog low voltage



## Digital signal from internal source

Digital - 3 wire / 2 position


Digital - 4 wire / 3 point floating


Digital signal

## Digital - 3 wire / 2 position

COMMON


Digital - 4 wire / 3 point floating


## Special consideration for Digital control

In this mode, the actuator is sensitive to induced electrical voltages from external sources. To prevent such interference, if the signal on pins 4 and 3 on TB1 are from an external 24 Vac source, install a resistor $2.2 \mathrm{kohm}, 0.5 \mathrm{~W}$ between pins 4 and 1 and another of 2.2 kohms , 0.5 W between pins 3 and 1 of TB1. These resistors are included.

## Input Signal and Feedback setup

|  | Input Signal | Feedbac k |
| ---: | :---: | :---: |
| Analog Mode | Input Signal is set with Dipswitch \#3 <br> DS1-3 at OFF $=2-10 \mathrm{Vdc}$ (default setting) <br> DS1-3 at ON $=4-20 \mathrm{~mA}$ |  |
| Digital \& PWMM | No Input Signal Setting | Feedback is set with Dipswitch \#4 <br> DS1-4 at OFF $=4-20 \mathrm{~mA}$ (default setting) <br> DS1-4 at ON $=2-10 \mathrm{Vdc}$ |
| ModeMode | DS1-3 MUST be at OFF |  |

## PC Board



## Stroke adjustment - No control signal change

1. Apply power and, WAIT FOR LED TO BE OFF (around $\mathbf{1 0}$ seconds).
2. Press and release the reset button to start the auto-stroke process. The LED should be illuminated.

- First option:

The actuator will then travel in both directions to find its limit and position itself according to the demand. The LED will extinguish, the process is complete.

- Second option:

When the desired start position is reached, press and release the reset button. The actuator will now go the end position. (you can also press and release the reset button when It's reaches the end position) The LED will extinguish, the process is complete.

## Programming - Change of control signal\& PWM pulse setting

1. Remove power and put all dip switches "OFF". (factory preset).
2. Apply power and, within $\mathbf{1 0}$ seconds, press and release the reset button. The LED should be blinking.
3. Select the control signal with dip switches:

|  | Digital or Analog Modes | PWM Mode |
| :---: | :---: | :---: |
| Move switch No1 "ON" and then "OFF". | Digital (On/Off or 3 point floating) | 5 sec. pulse (factory preset) |
| Move switch No2 "ON" and then "OFF". | Analog (Default) | 25 sec. pulse |

## 4. Stroke adjustment

see the stroke adjustment section above.

## Enabling or disabling PWM mode

1. Remove power supply to actuator
2. Install jumper between pin $3 \& 4$ of J 3
3. Select the desired action using the dipswitches (DS1):

| DS1-1 | DS1-2 | Action |
| :---: | :---: | :---: |
| OFF | ON | Enable PWM Mode |
| ON | OFF | Disable PWM Mode |

4. Re-apply power supply to actuator
5. Wait 5 seconds
6. Remove power supply to actuator
7. Remove jumper between pin 3 \& 4 of J3, re-install it between pin $4 \& 5$.
8. Re-apply power supply to actuator

PWM is factory preset at 5 sec. pulse, refer to programming section above to change pulse setting.


When not used for programming, jumper is placed between pin 4 \& 5

## Zero and span calibration

This feature is applicable to analog control signal only.

1. Remove power and put all dip switches "OFF". (factory preset).
2. Apply power and, within $\mathbf{1 0}$ seconds press and hold the reset button until the LED blinks once.

The Zero and span calibration process then start.
3. Release the reset button. The LED is now constantly illuminated.
4. Apply new minimum voltage.

It can be any value between 0 to 7 Vdc , with an external 0 to 10 volt supply (ex: MEP).
5. Press and release the reset button to memorize the new minimum voltage. The LED blinks.
6. Apply new maximum voltage.

It can be any value between 3 to 10 Vdc , this value should be greater than the new minimum value.
7. Press and release the reset button to memorize the new maximum voltage. The LED blinks.

The Zero and span calibration process is complete.

Note: To reset zero and span to 2 to 10 Vdc (factory value). You just have to re-select the analog control signal mode, see Programming.

Wiring Diagrams for auxiliary switches (on model 120\& 180)



[^0]:    We strongly recommend that all Neptronic ${ }^{\text {® }}$ products be wired to a separate transformer and that transformer shall service only Neptronic ${ }^{\circledR 8}$ products. This precaution will prevent interference with, and/or possible damage to incompatible equipment.
    When multiple actuators are wired on a single transformer, polarity must be observed. Long wiring runs create voltage drop which may affect the actuator performance.

[^1]:    ${ }^{1}$ Enerdrive SystemU.S.A. Patent \#5,278,454

